

## Simulation-Based Inference of Reionization Parameters From 3D Tomographic 21 cm Lightcone Images

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<sup>3</sup>*Sorbonne Université, CNRS, UMR 7095, Institut d'Astrophysique de Paris (IAP), 98 bis bd Arago, 75014 Paris, France*

<sup>4</sup>*Sorbonne Université, Institut Lagrange de Paris (ILP), 98 bis bd Arago, 75014 Paris, France*

<sup>5</sup>*Center for Computational Astrophysics, Flatiron Institute, 162 5th Avenue, New York, NY 10010, USA*

Astro-ph/ 2105.03344

# Hayato Shimabukuro

## (Take home messages)

- **Simulation-based inference (SBI)** constructs Likelihood through forward simulation by using **Density estimation likelihood-free inference (DELFI)**
- **SBI** + **machine learning** + **Bayesian inference** → **posterior distribution**

# Theory

(e.g) cosmological model

$\Omega_{\text{tot}}, \Omega_b, \Omega_m, \Omega_\Lambda, H_0, n_s \dots$

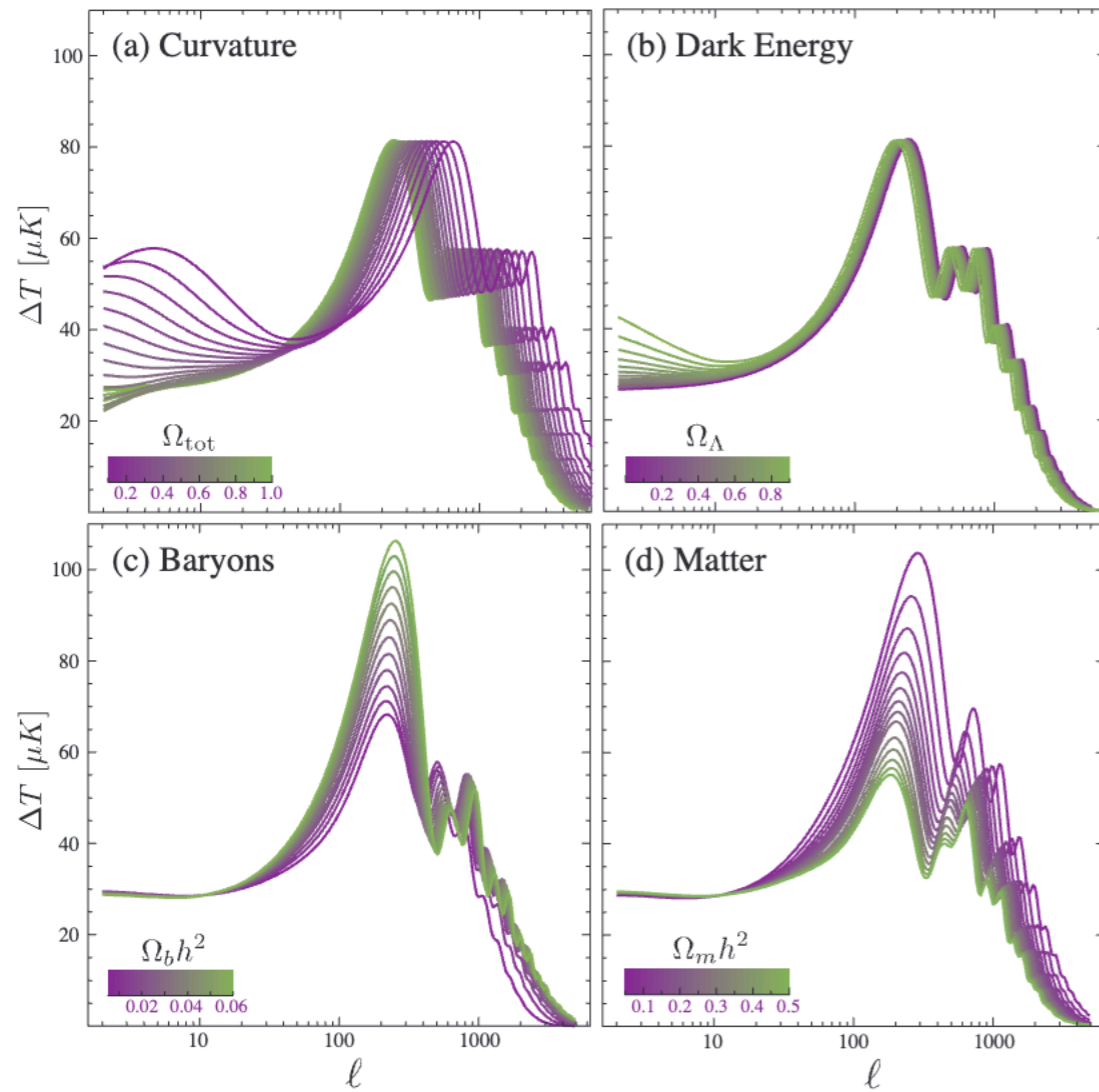
• A model is characterized by parameters.

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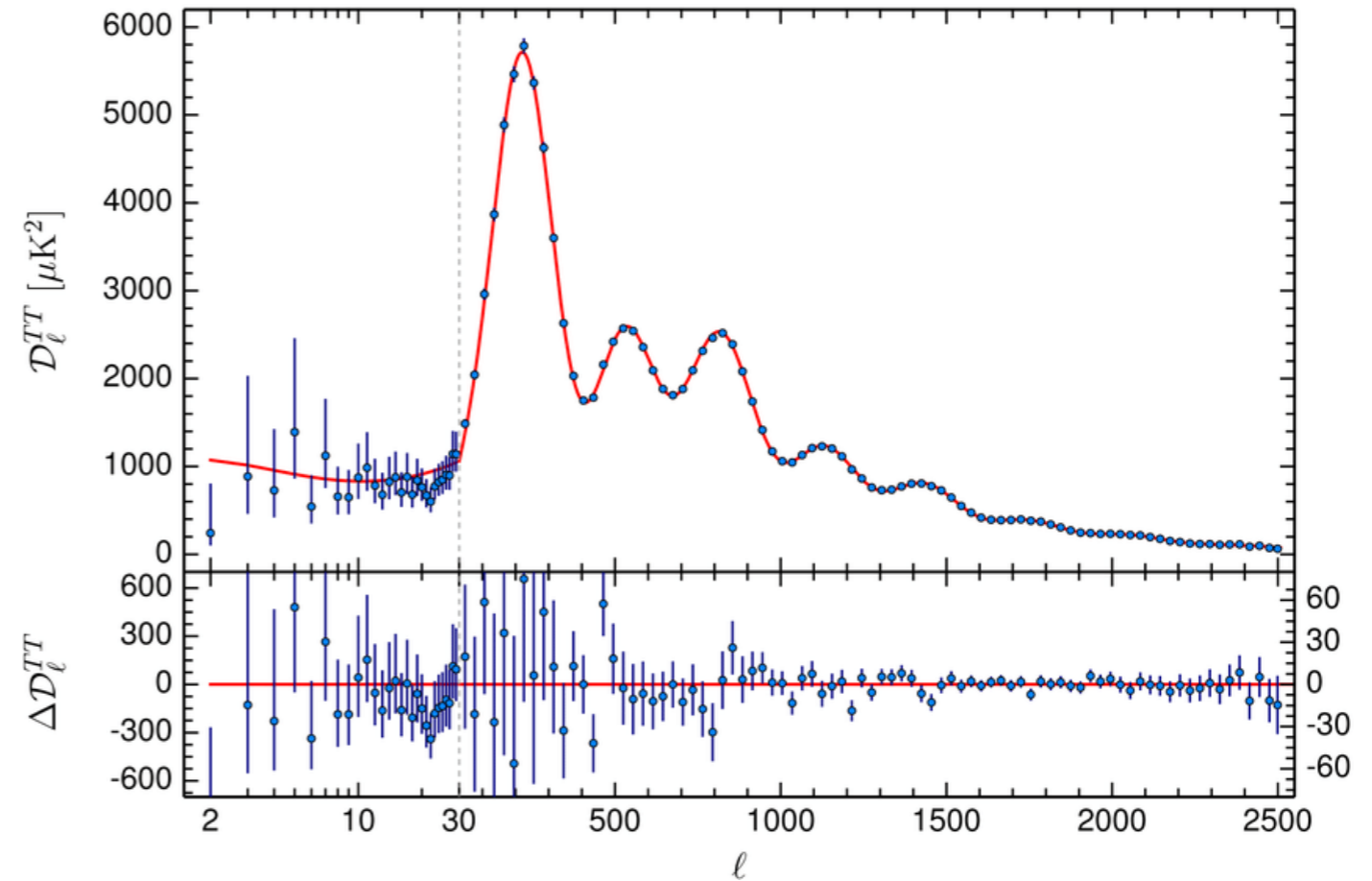
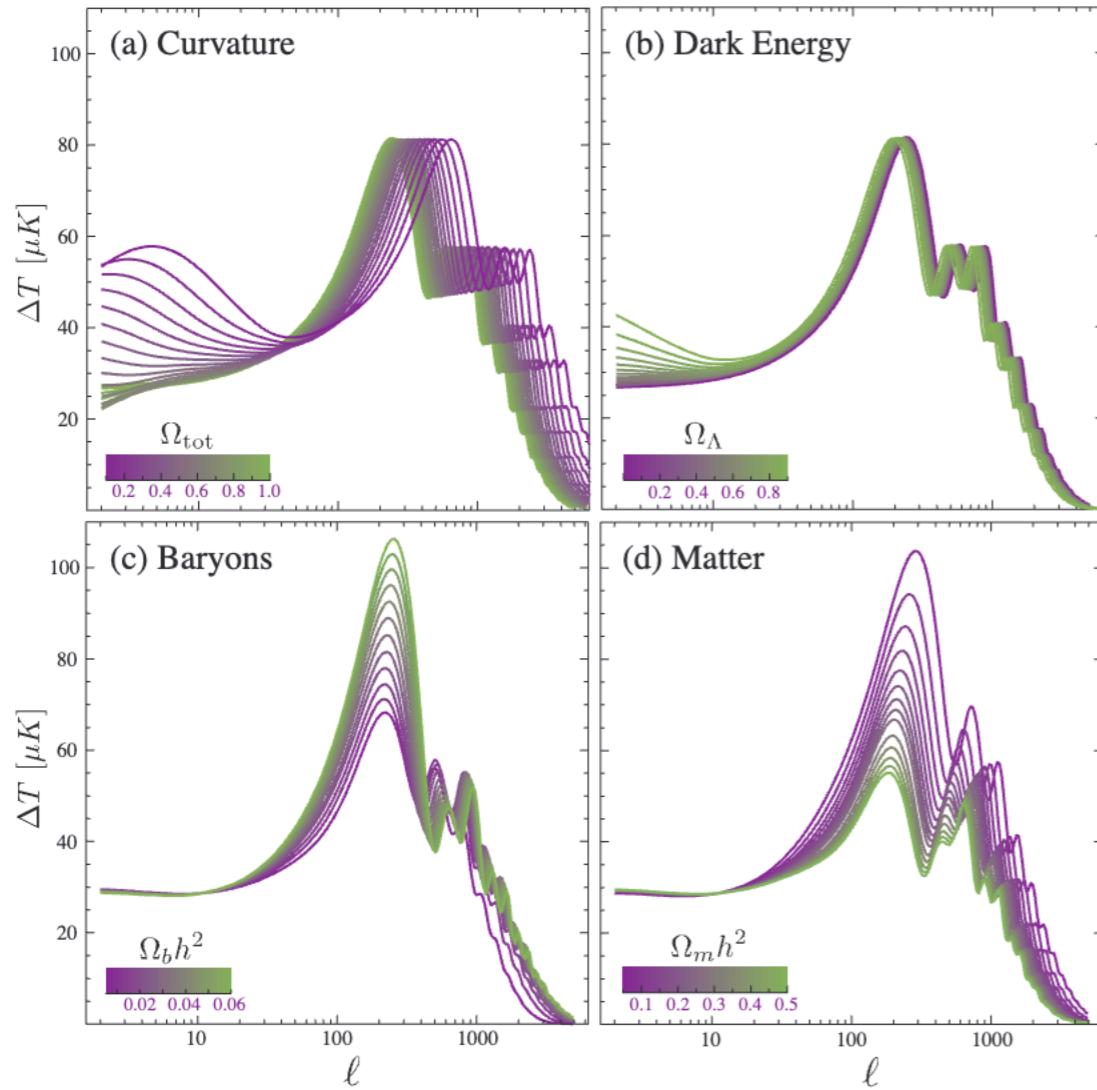
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# Observations/experiments



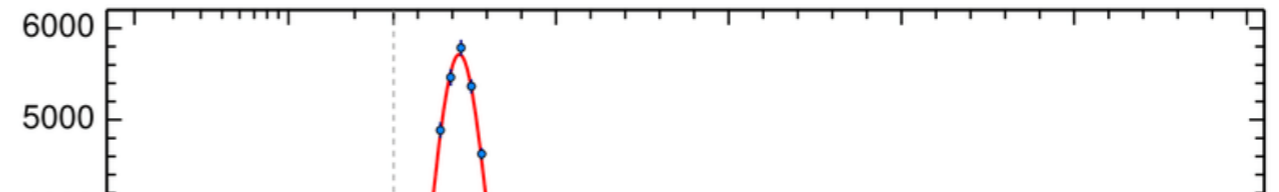
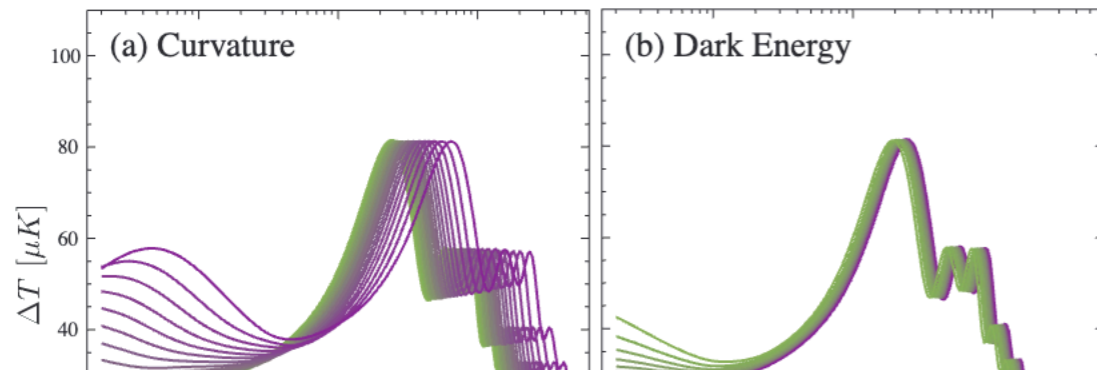
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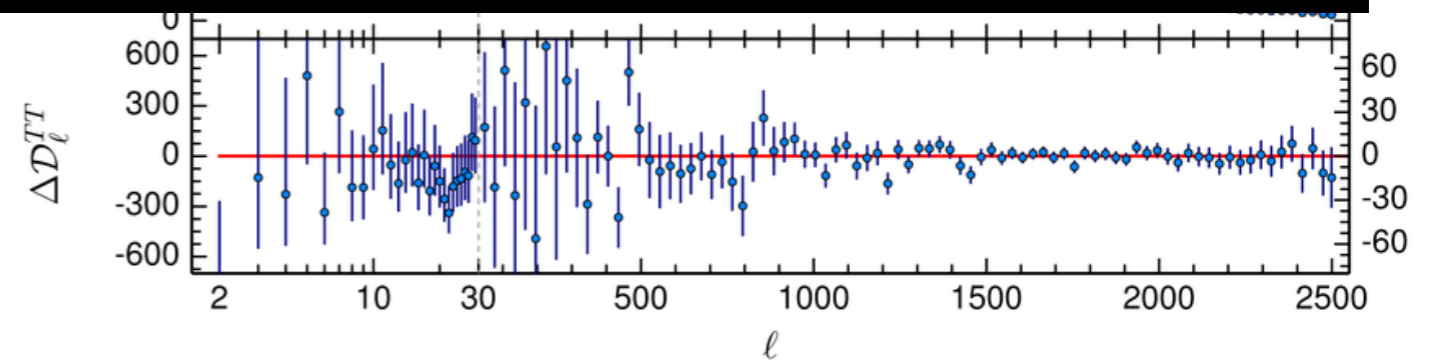
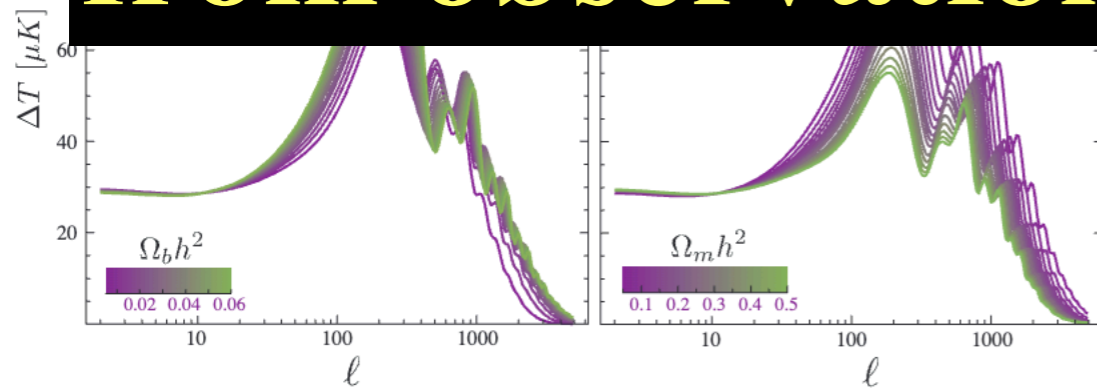
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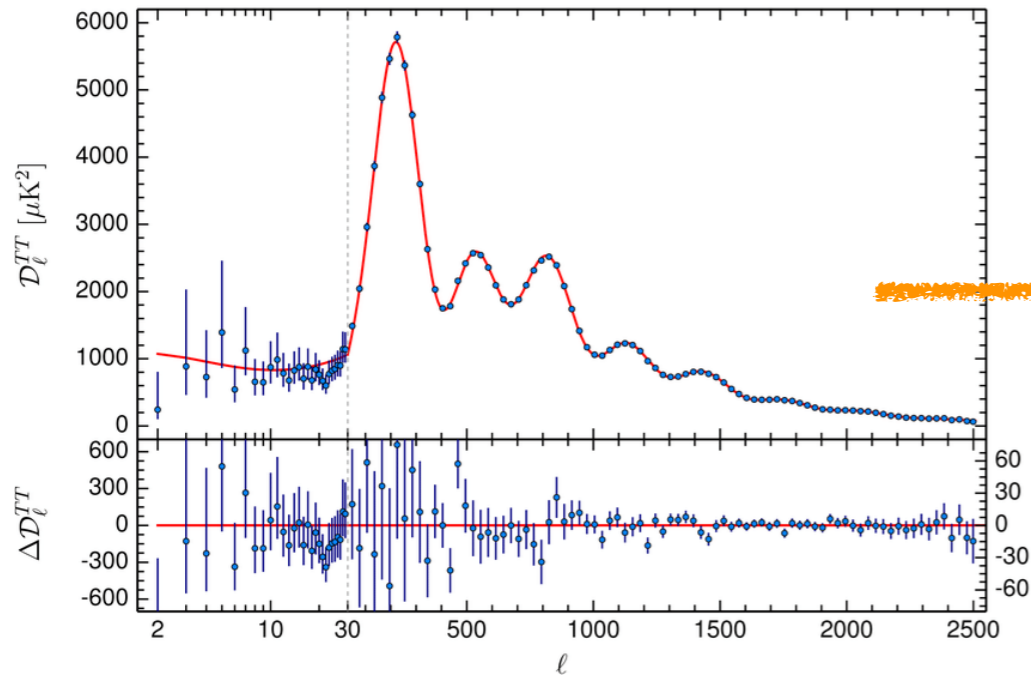
# Observations/experiments



**We would like to determine parameters from observational results!**

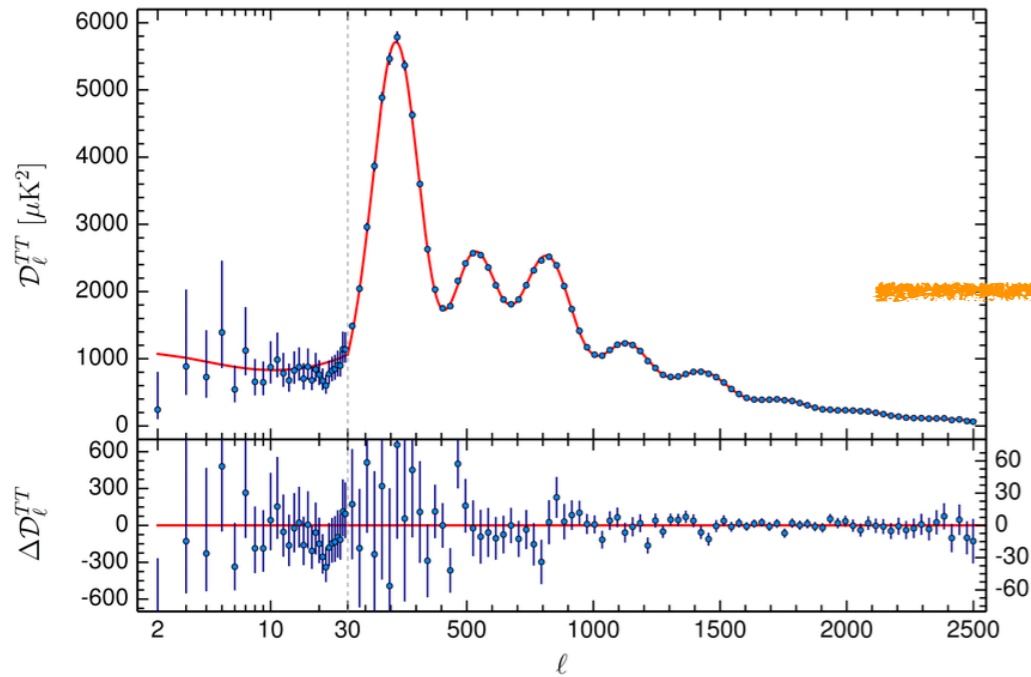


• For **given** observational results, what parameter sets are preferred??



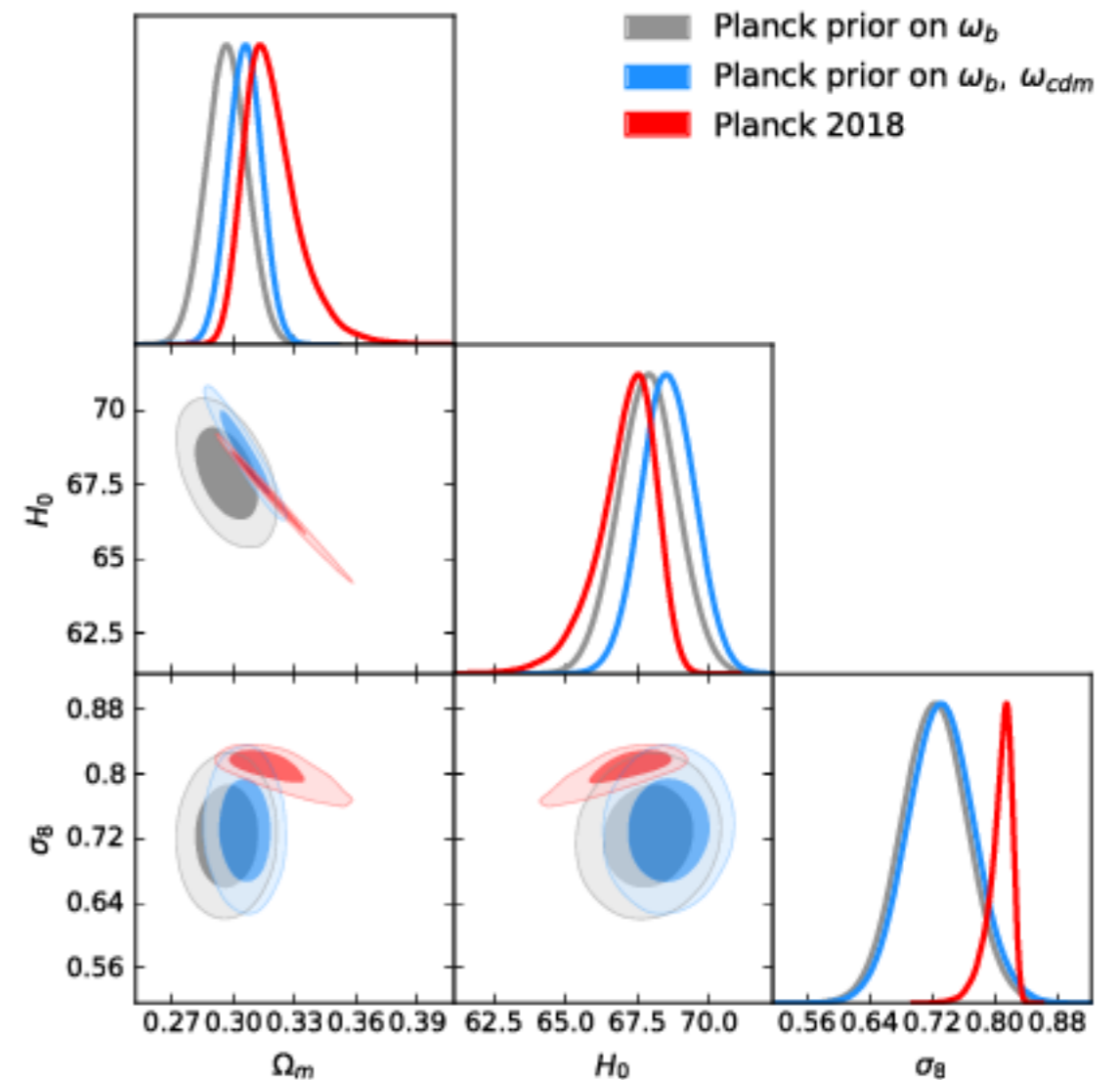
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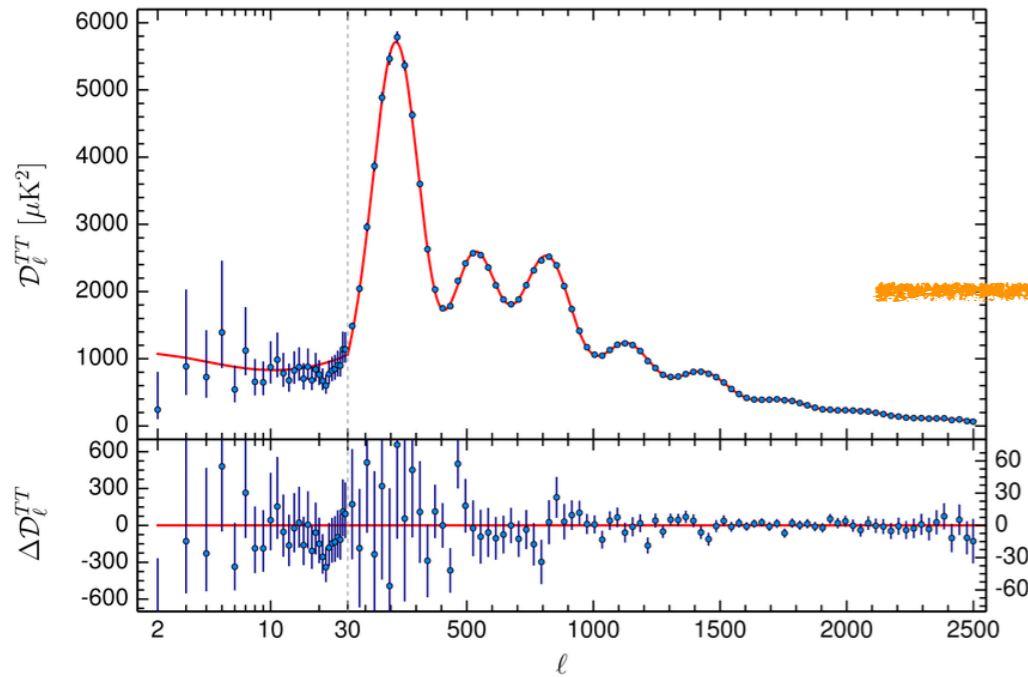


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• In **Bayesian inference**, we evaluate the **posterior distribution** of parameters with MCMC.



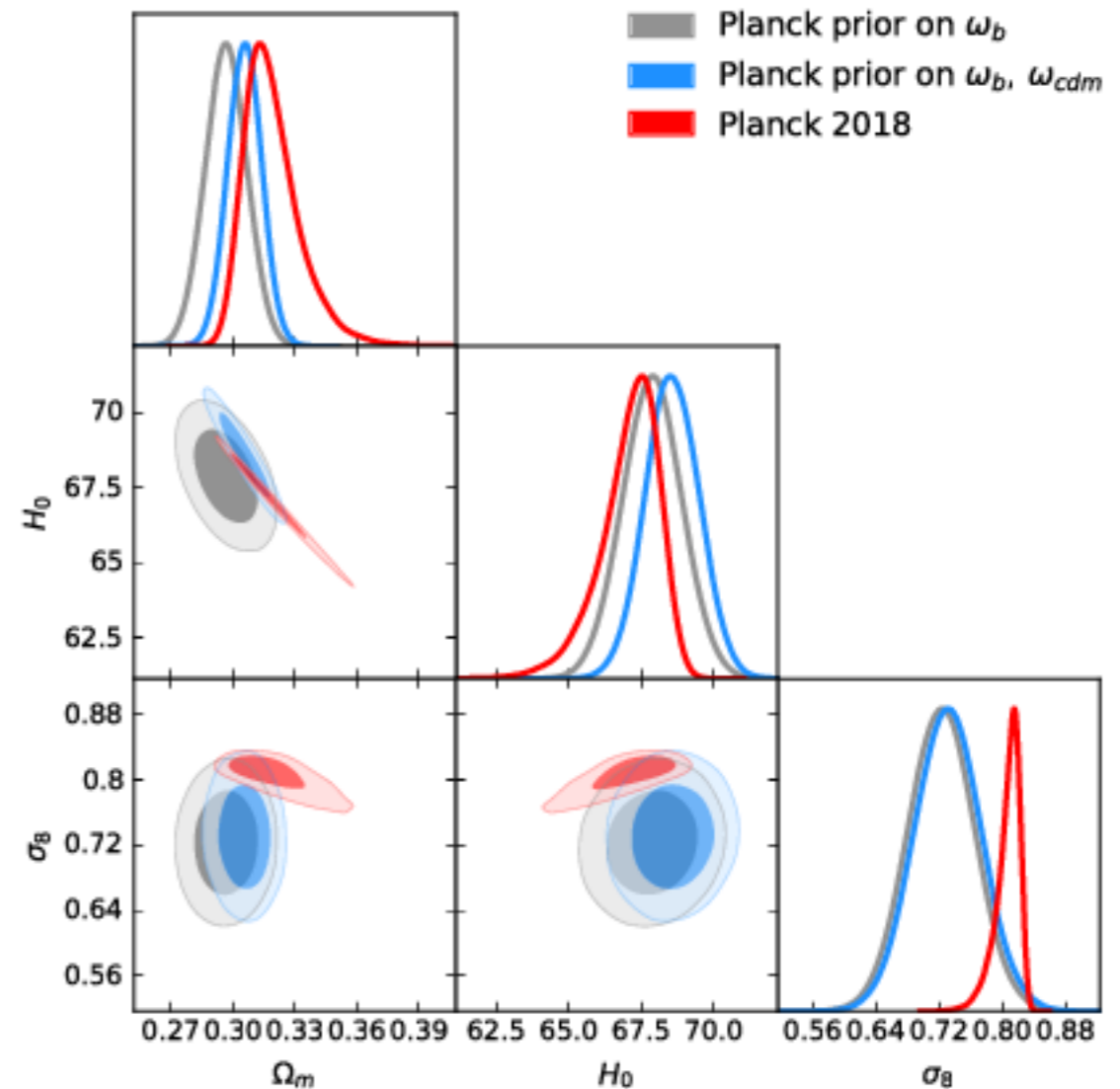
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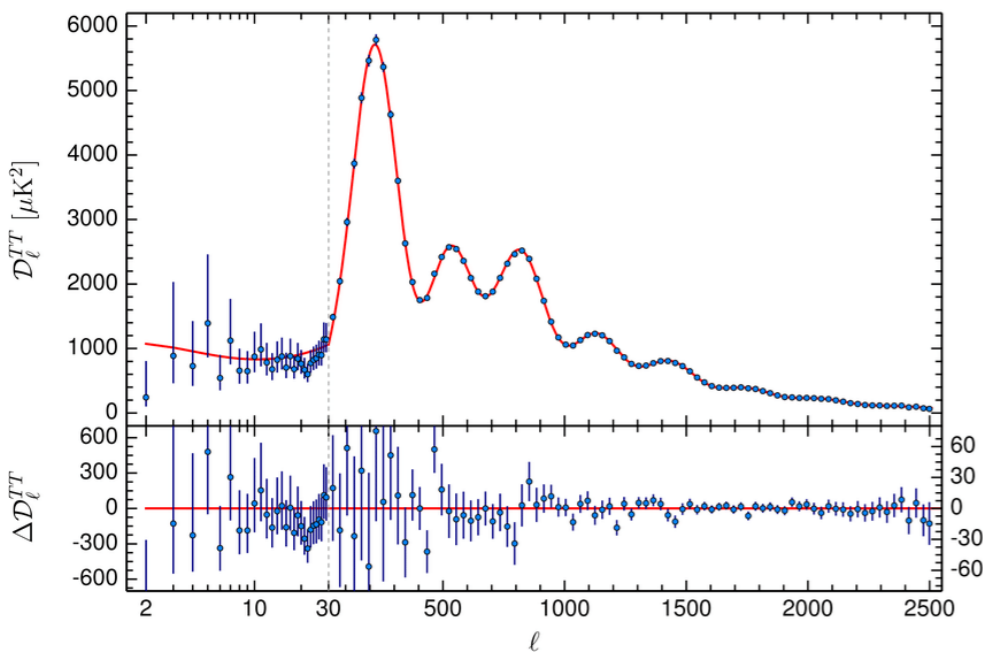
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*How do you obtain posterior distributions?*

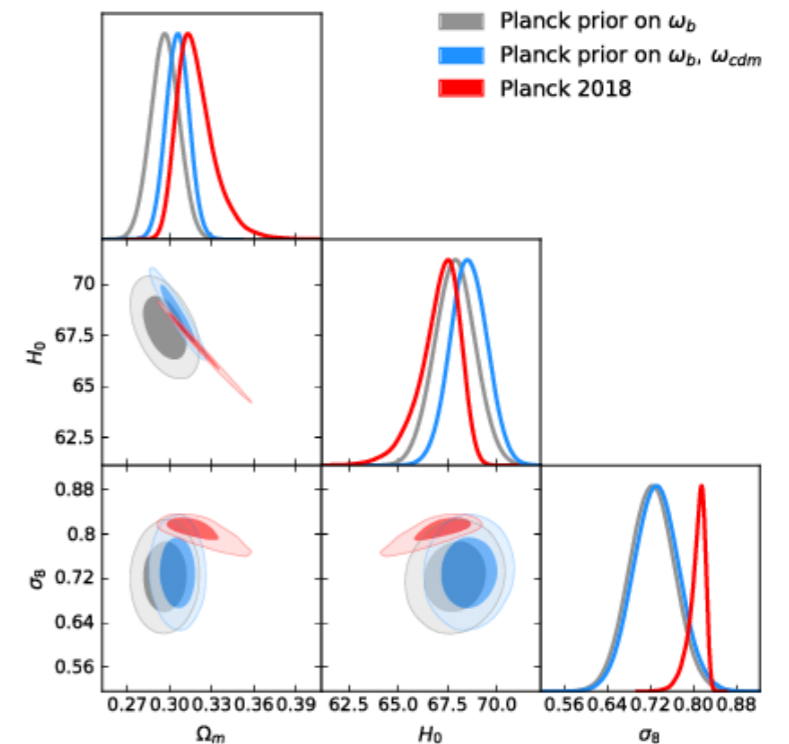






posterior  
 $p(\text{model} \mid \text{data})$

←————→



For **given data**, we evaluate which **theoretical parameter values** explain the data well.

Posterior
Likelihood
Prior

$$p(\theta \mid \mathbf{t}_0) \propto \mathcal{L}(\mathbf{t}_0 \mid \theta) p(\theta)$$

**(Key question 1)**

We usually assume Gaussian as likelihood. Can we use a more flexible likelihood?

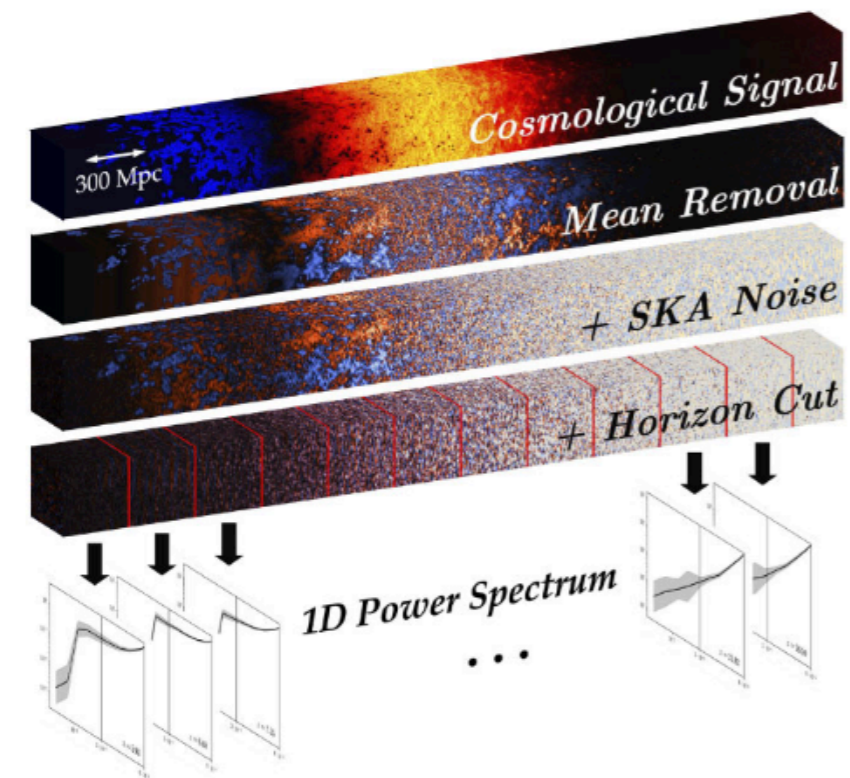
$$\mathcal{L}(t_0 \mid \theta) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

# Another parameter estimation approach

## Artificial Neural Network(ANN)

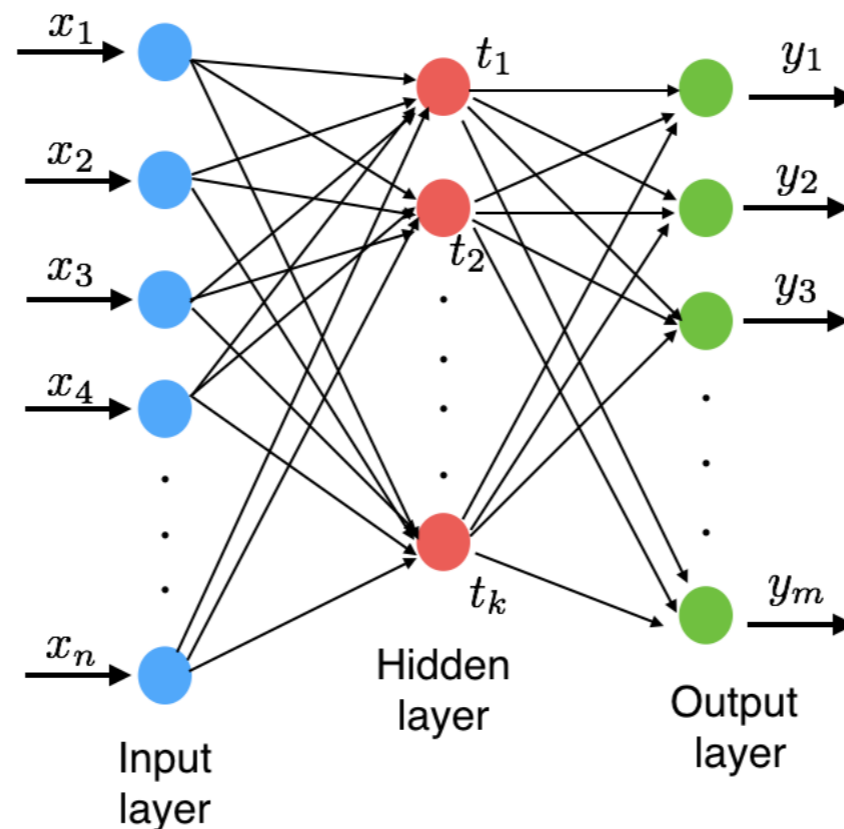
- The ANN is one of the machine learning techniques. Once we train the architecture of ANN by training the dataset, we can apply the trained network to unknown data sets.

### Input

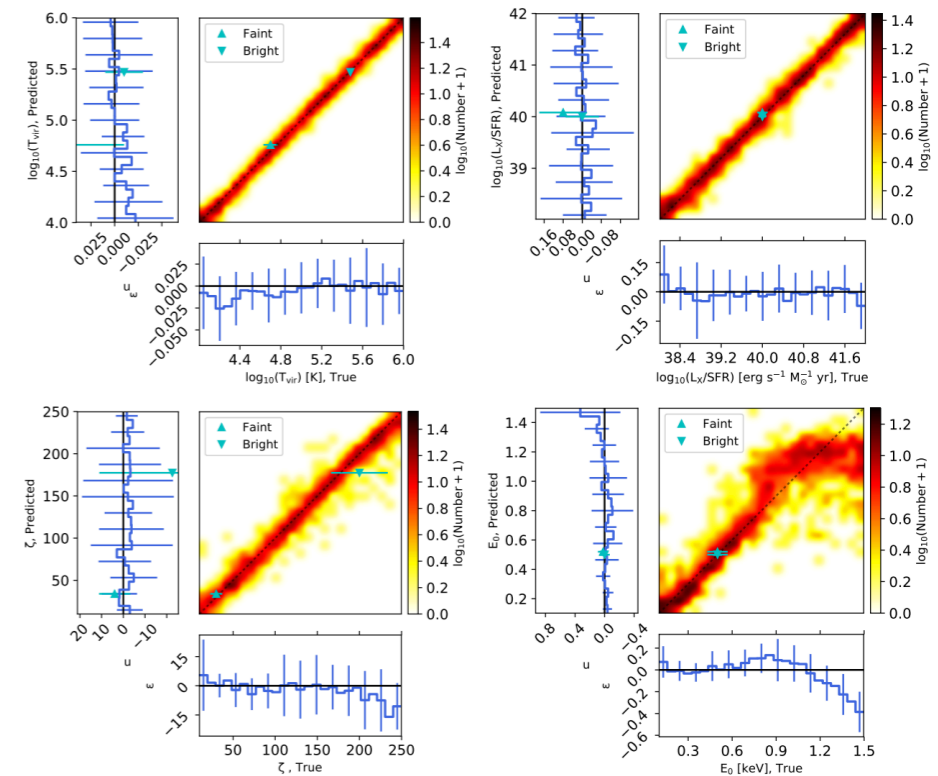


### Power spectrum, images

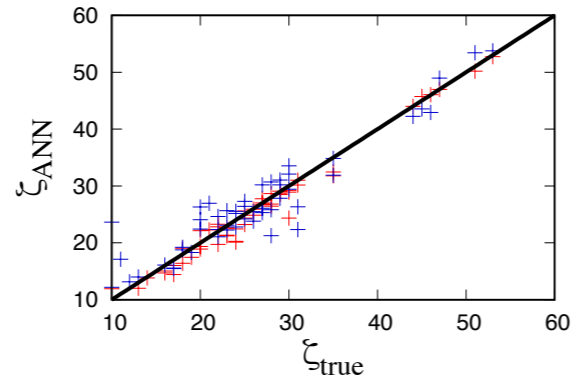
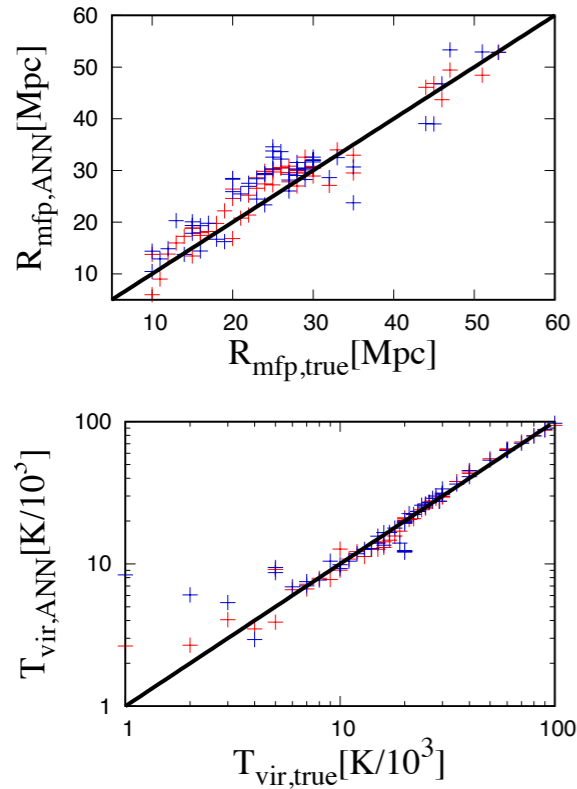
### ANN



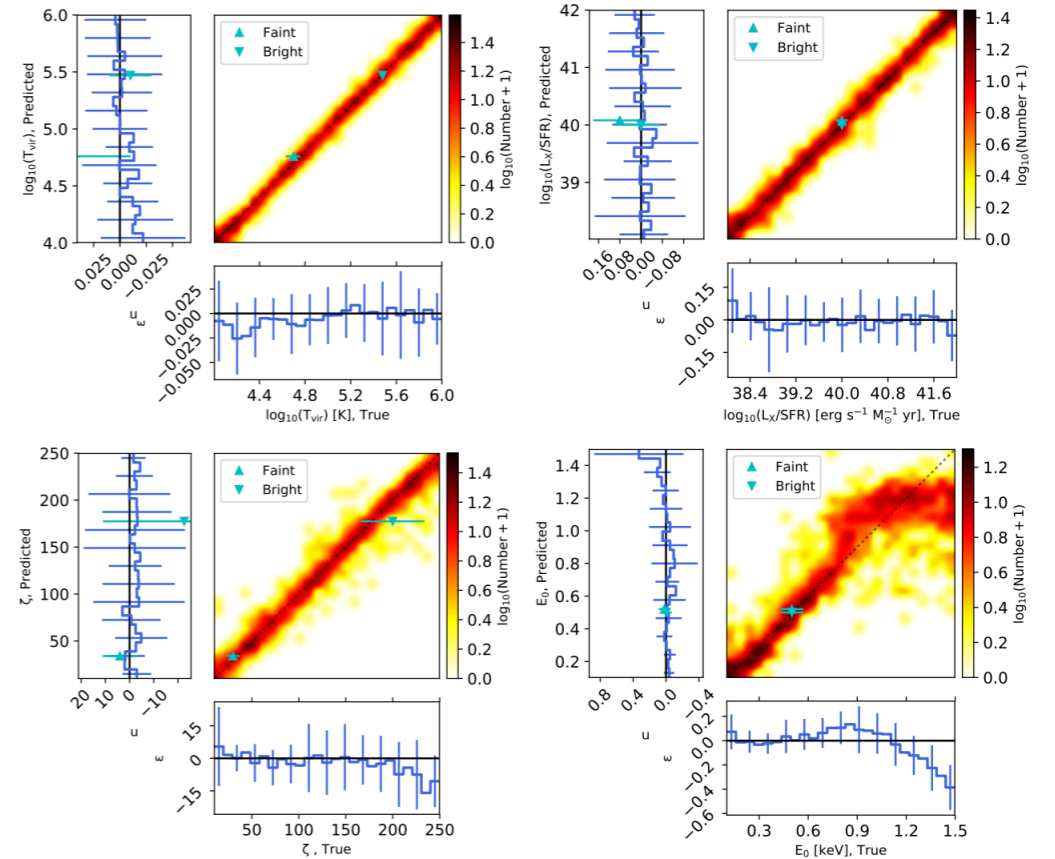
### Output



### Parameters

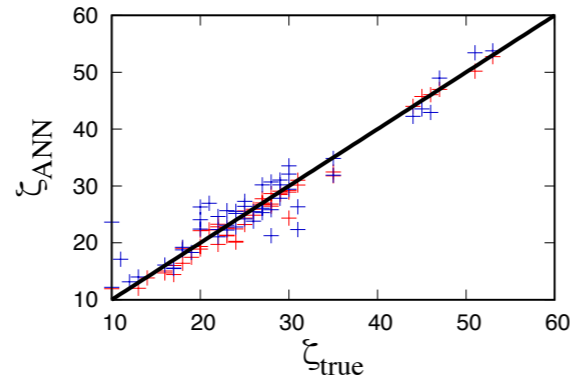
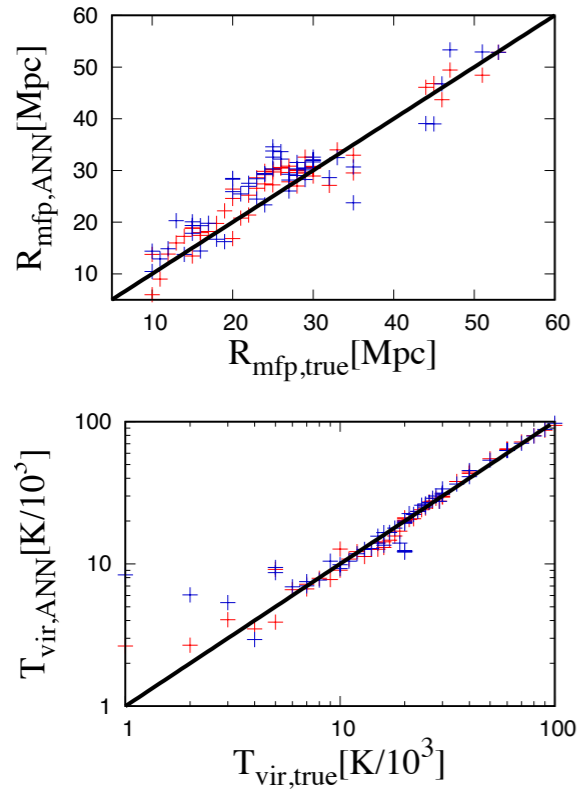


**Shimabukuro & Semelin(2017)  
, Gillet+ (2018),etc...**

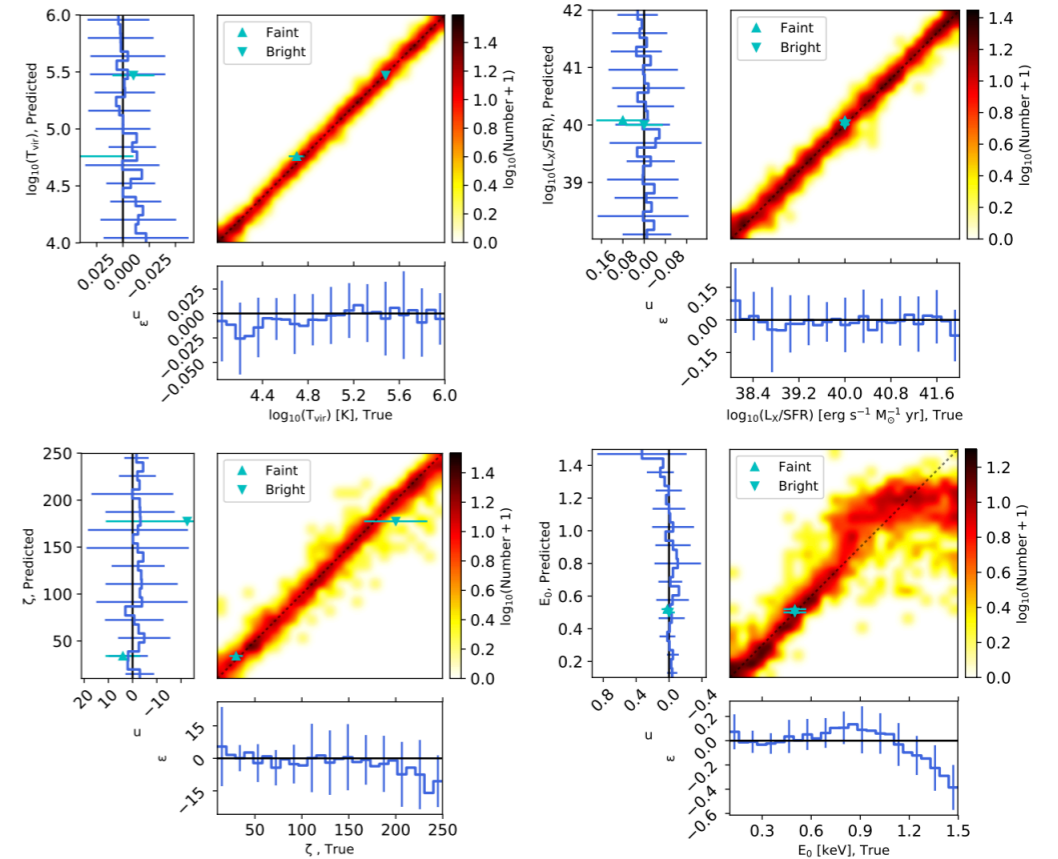


• We usually **DO NOT** evaluate the **uncertainty** of machine learning itself. ANN just returns “points”.

• In Bayesian inference with MCMC, we need to calculate likelihood (and prior) to obtain the posterior of parameters.



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**Key question 2.**

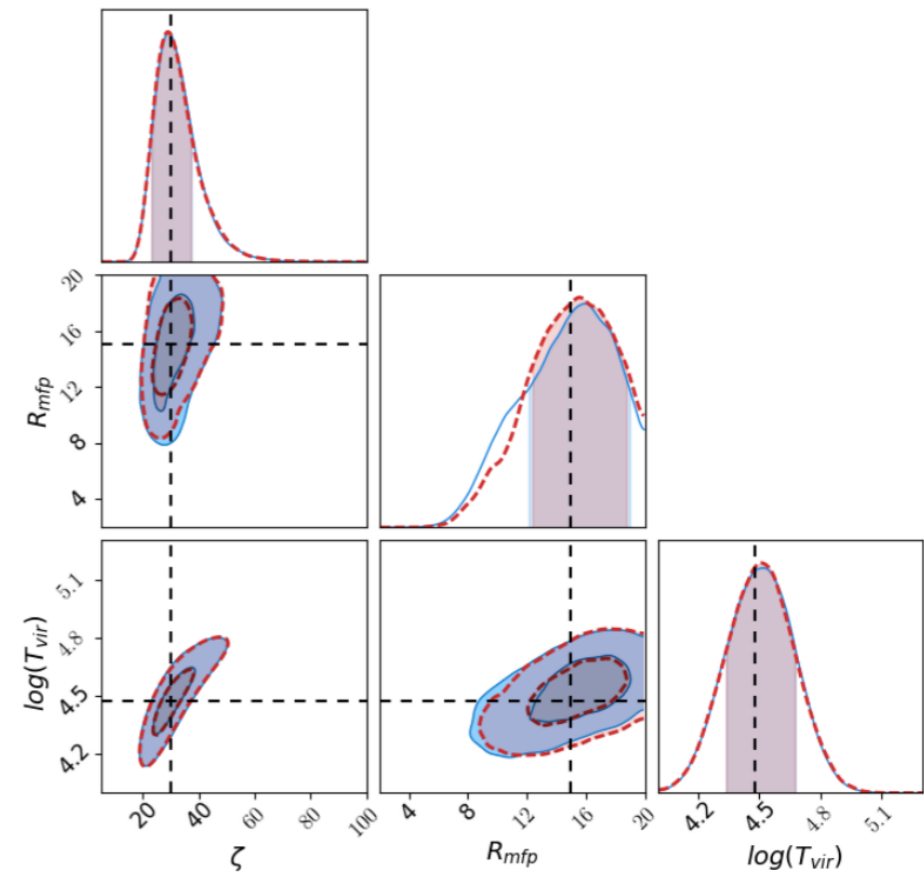
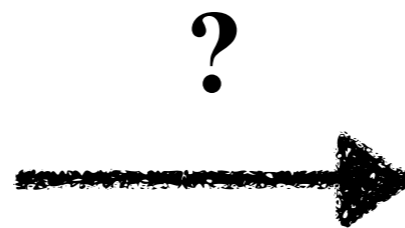
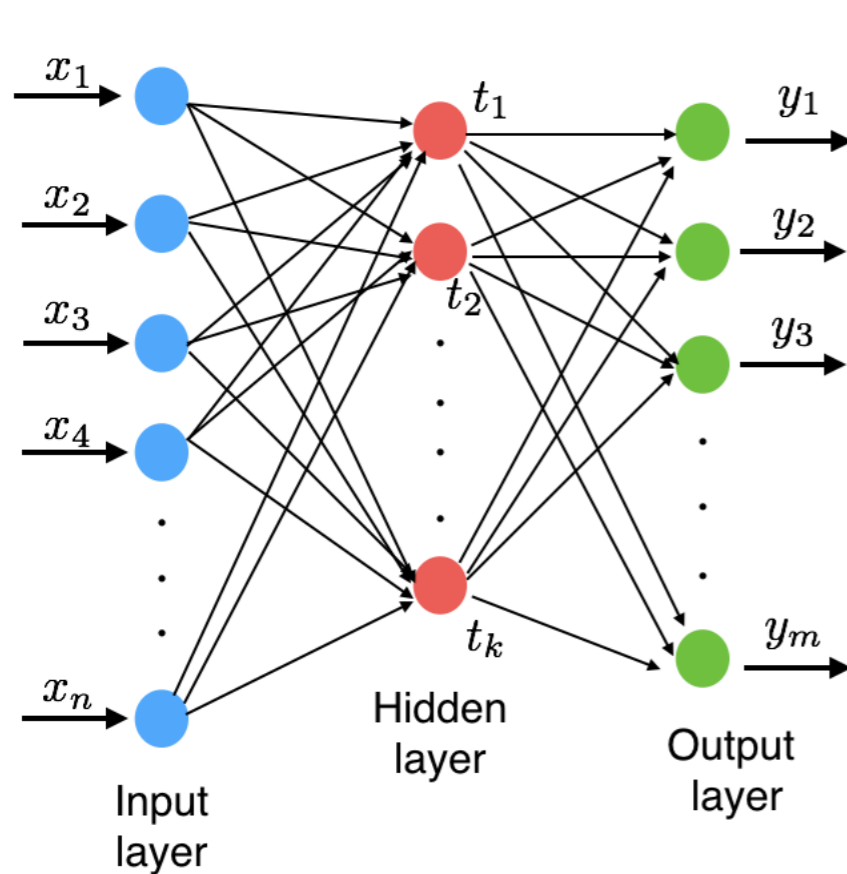
**Can we obtain posterior with ANN direct parameter estimate?**

# Key Questions

Q1. We usually assume Gaussian as likelihood. Can we use a more flexible likelihood?

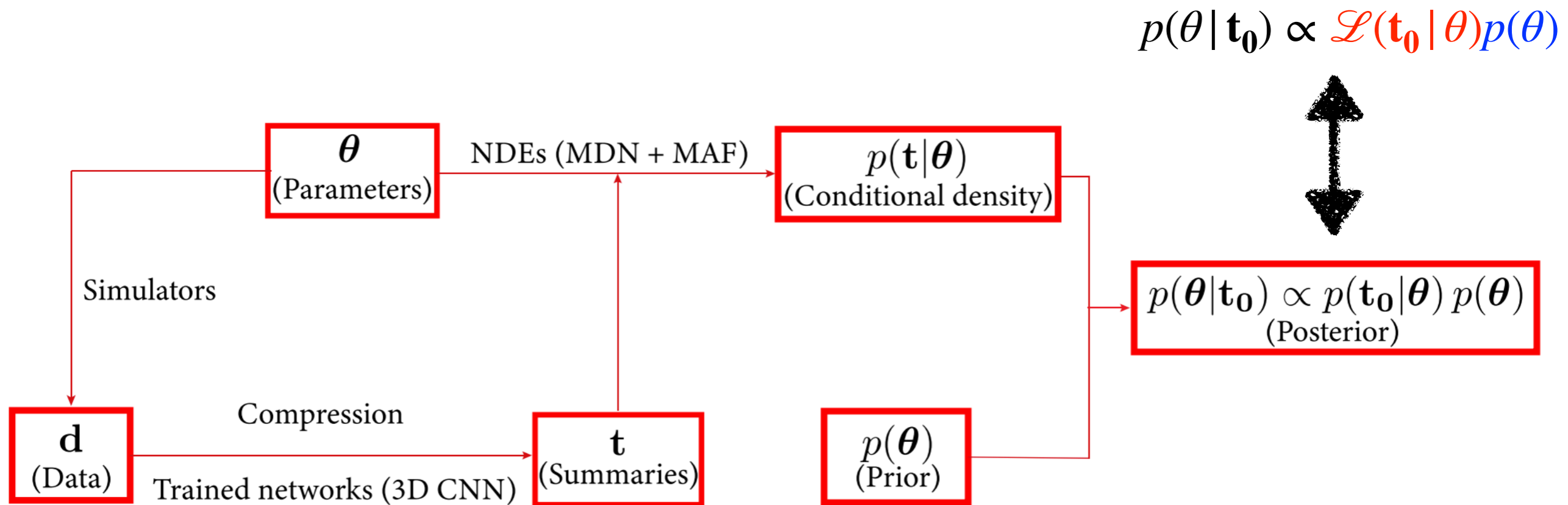
$$p(\theta | \mathbf{t}_0) \propto \mathcal{L}(\mathbf{t}_0 | \theta) p(\theta) \quad \mathcal{L}(t_0 | \theta) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

Q2. Can we obtain the posterior with an ANN direct parameter estimate?



# Posterior inference with machine learning

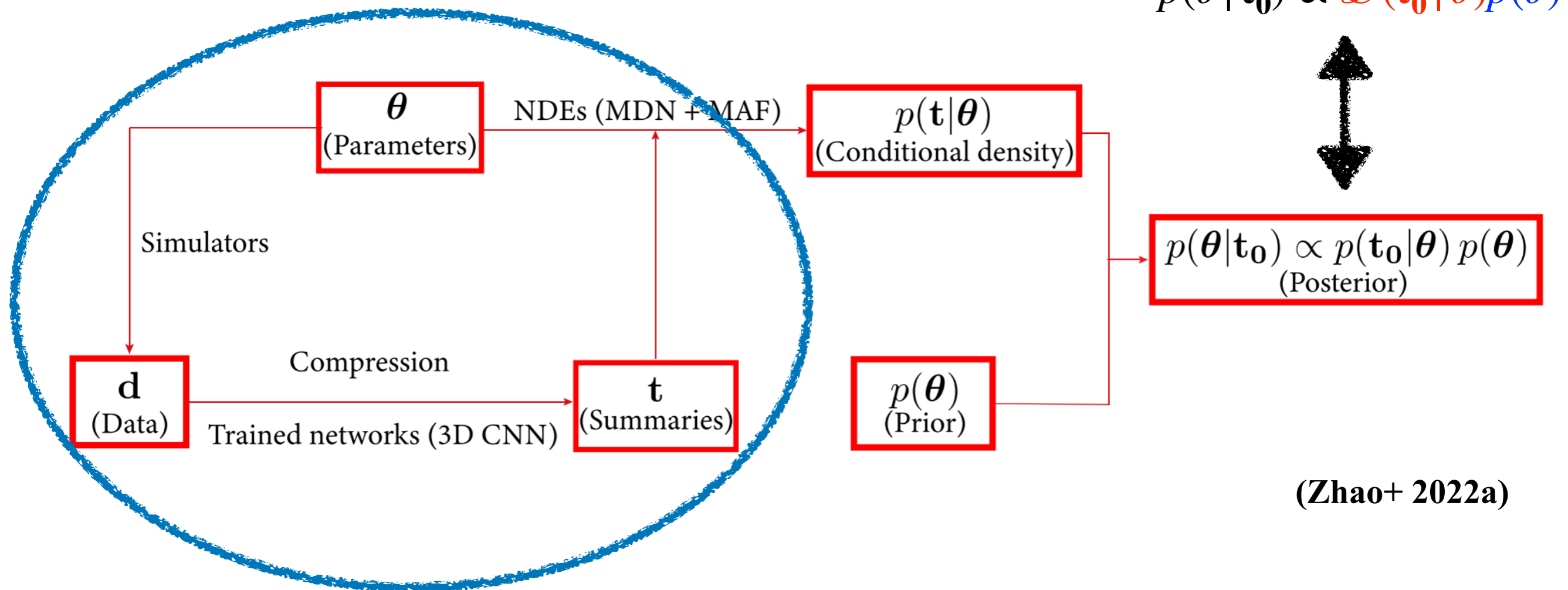
- This paper suggested a “**likelihood-free**” approach (**DELFI**, *Density estimation likelihood-free inference*) or **simulation-based inference** in 21cm study. They consider **conditional density distribution** instead of likelihood.



(Zhao+ 2022a)

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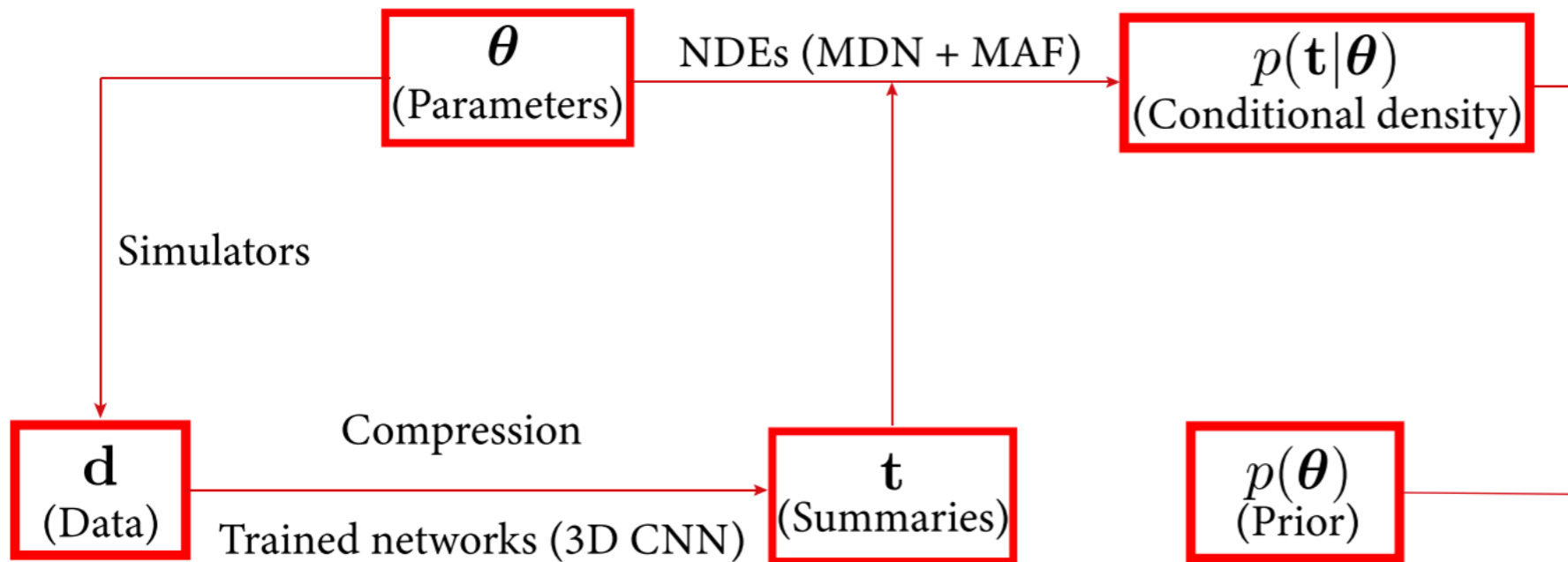


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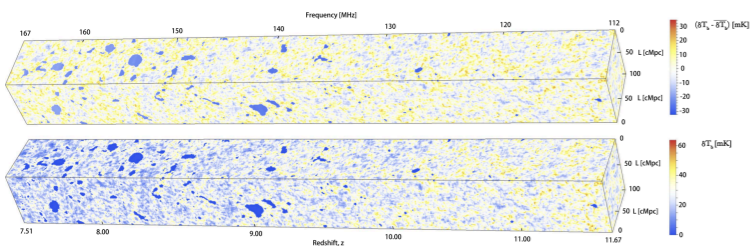
(Posterior)

$$p(\theta)$$

(Prior)



(Zhao+ 2022a)



Data: 21cm image



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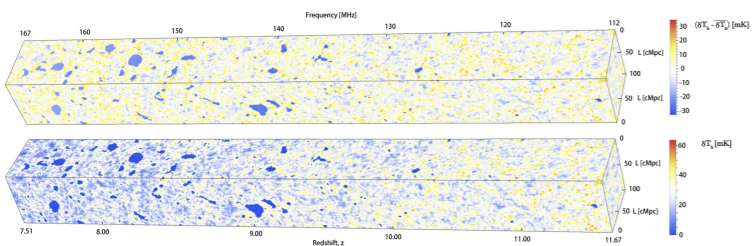
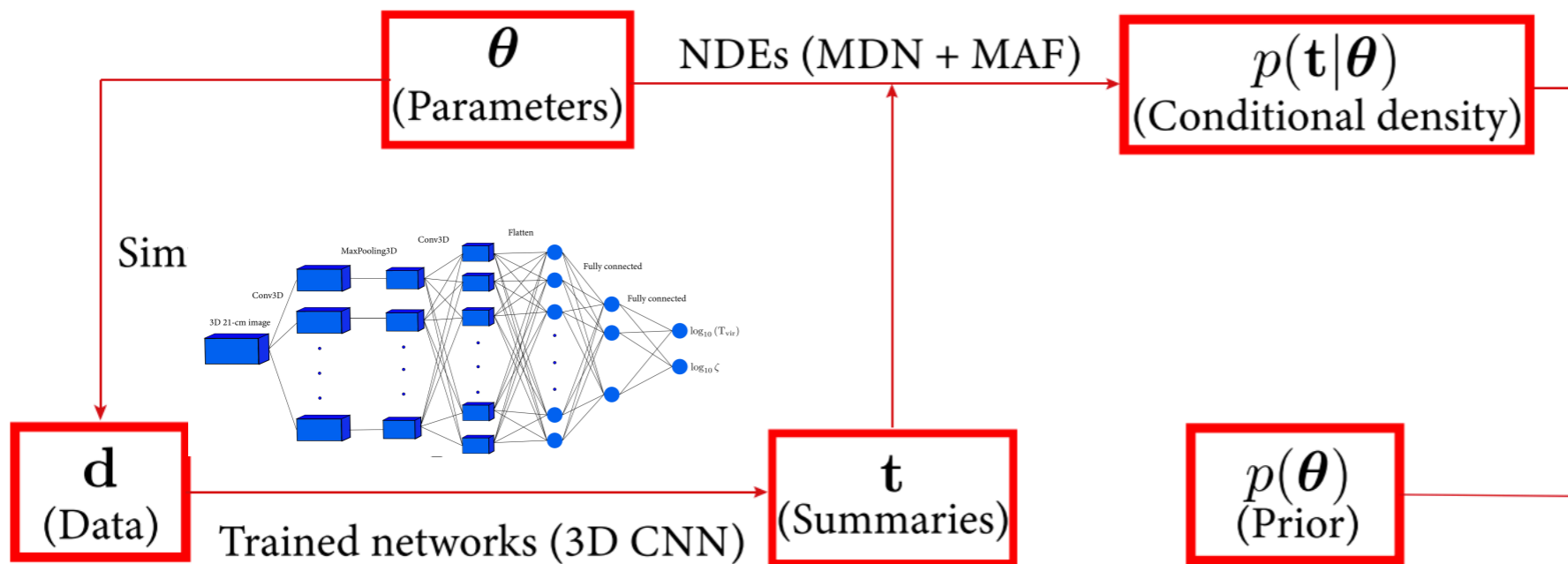
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(Posterior)



**Data: 21cm image**

(Zhao+ 2022a)

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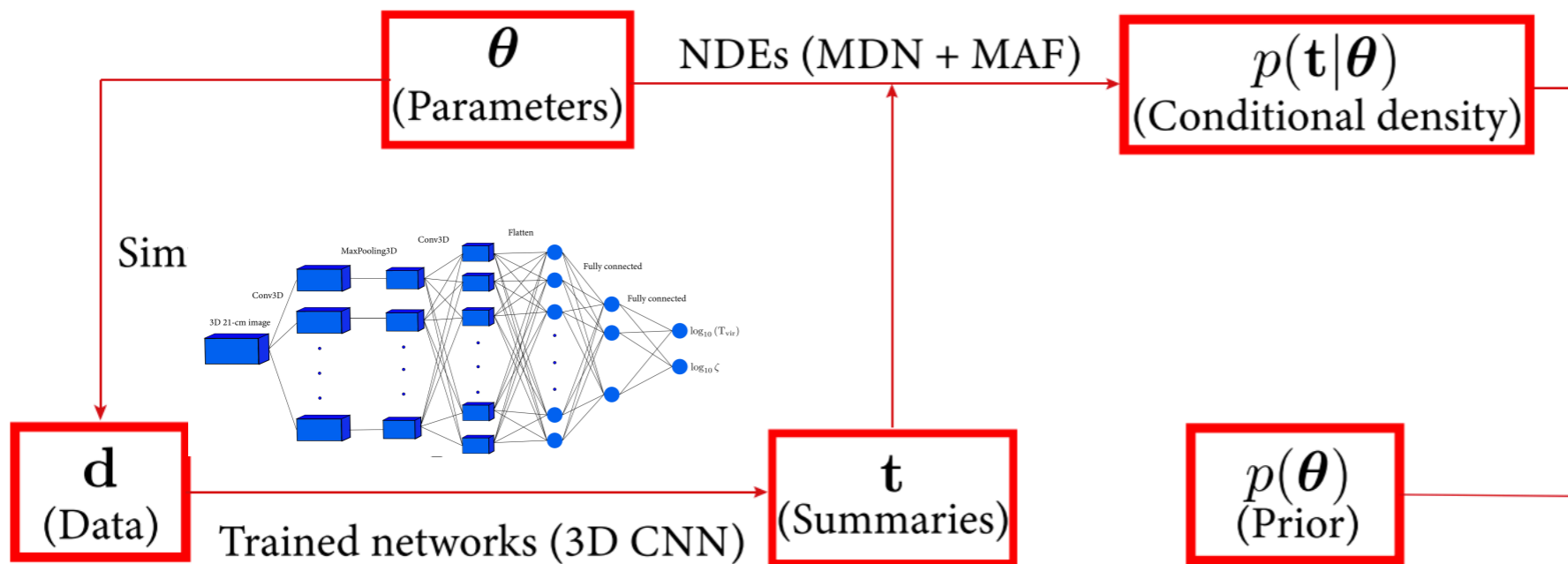
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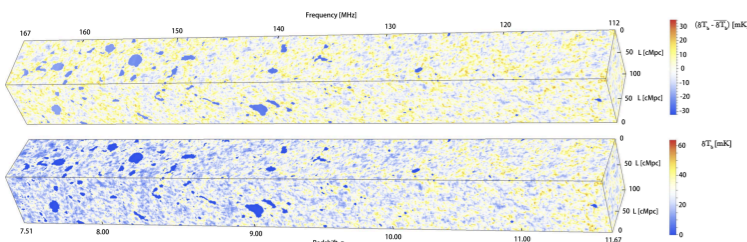
(Posterior)



(Zhao+ 2022a)

**Summaries:**  
**EoR parameters** ( $T_{vir}$ ,  $\zeta$ )

**Data: 21cm image**



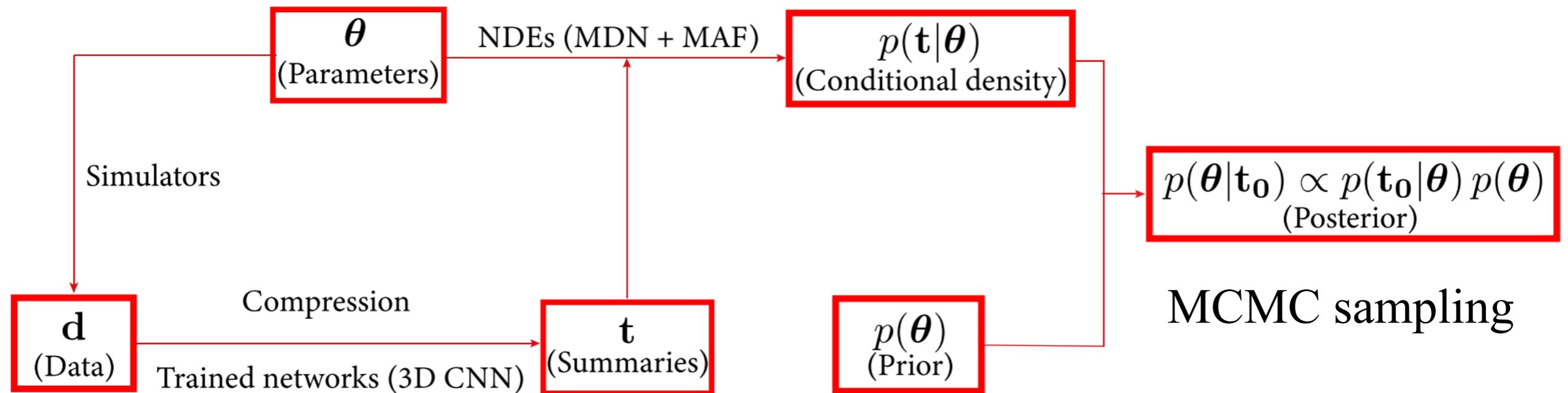
# Posterior inference with machine learning

We train neural networks with  $\{\theta, t\}$  and obtain conditional density  $p(\mathbf{t} | \theta)$  based on simulations.

- Mixture density networks (MDN) (Bishop 1994)
- Masked Autoencoder for Density Estimation (MADE) (Papamakarios+ 2017)

(See also Alsing+2019)

Training dataset  $\{\theta, \mathbf{t}\}$



(Zhao+ 2022a)

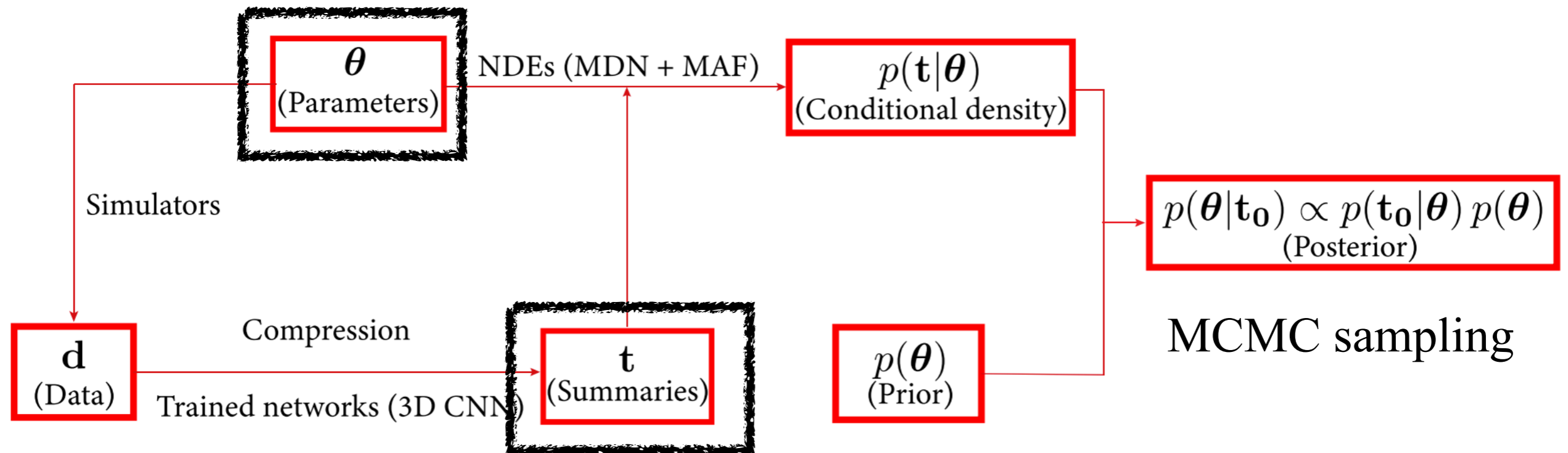
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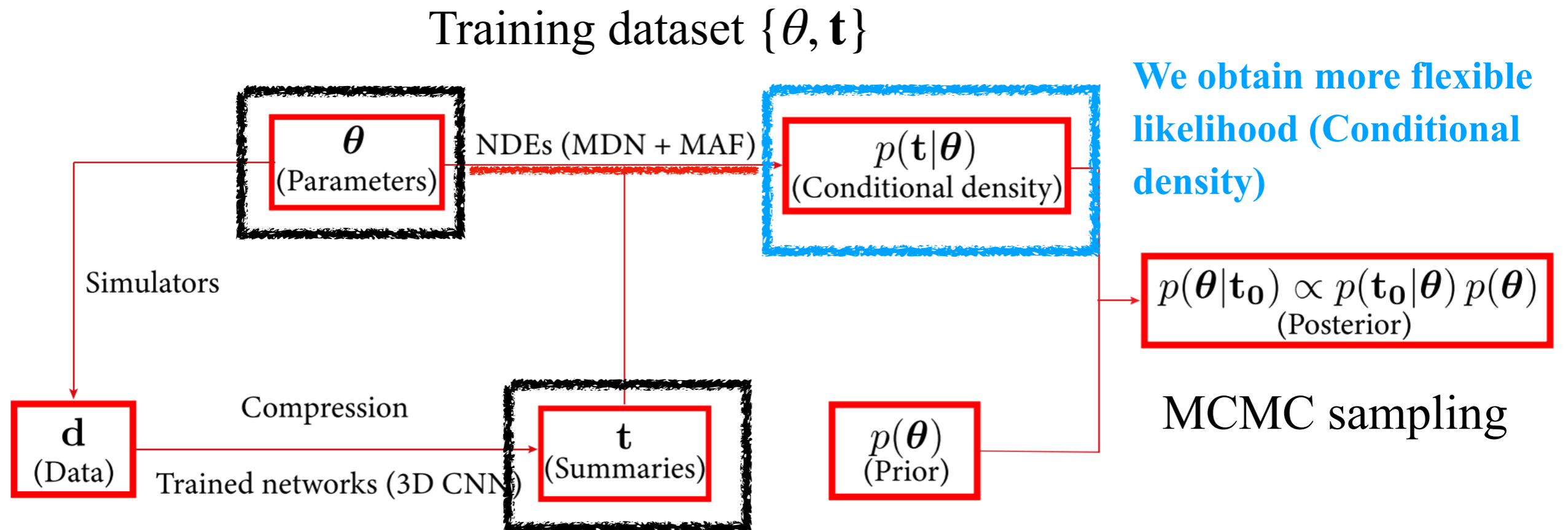


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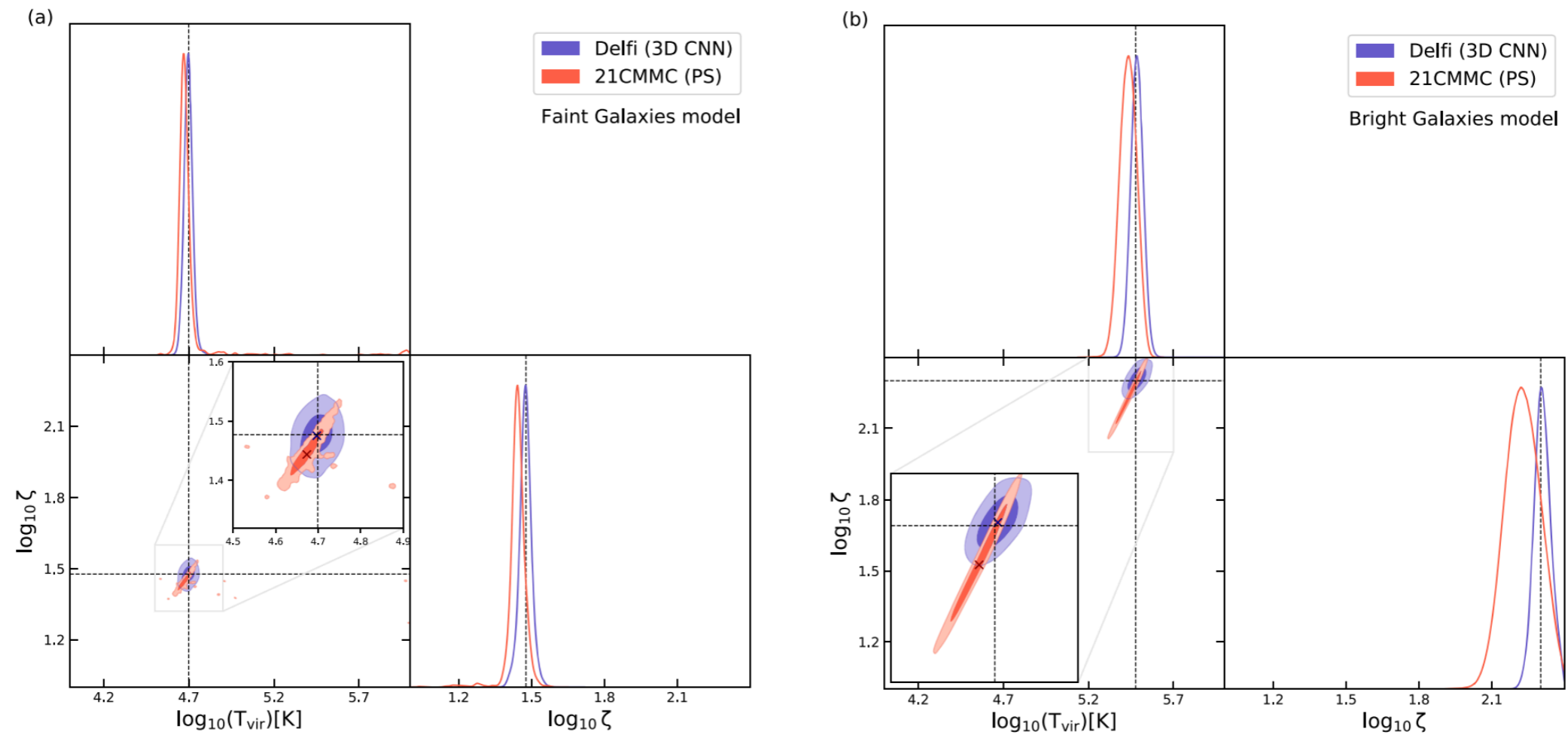
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# Posterior from 21cm image and PS

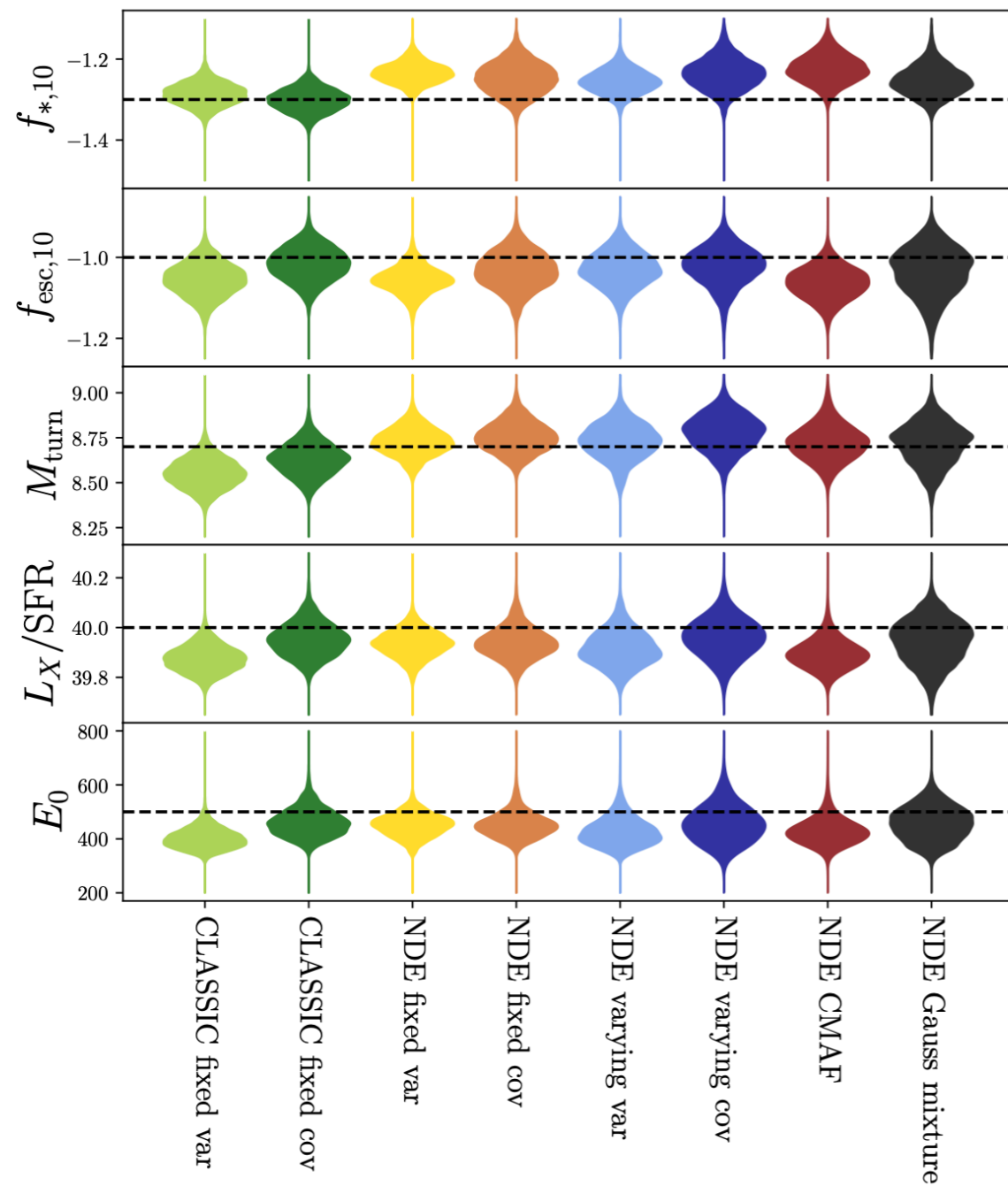
- We can directly compare the **posterior** obtained from **21cm image map** with the posterior obtained from 21cm PS with MCMC.



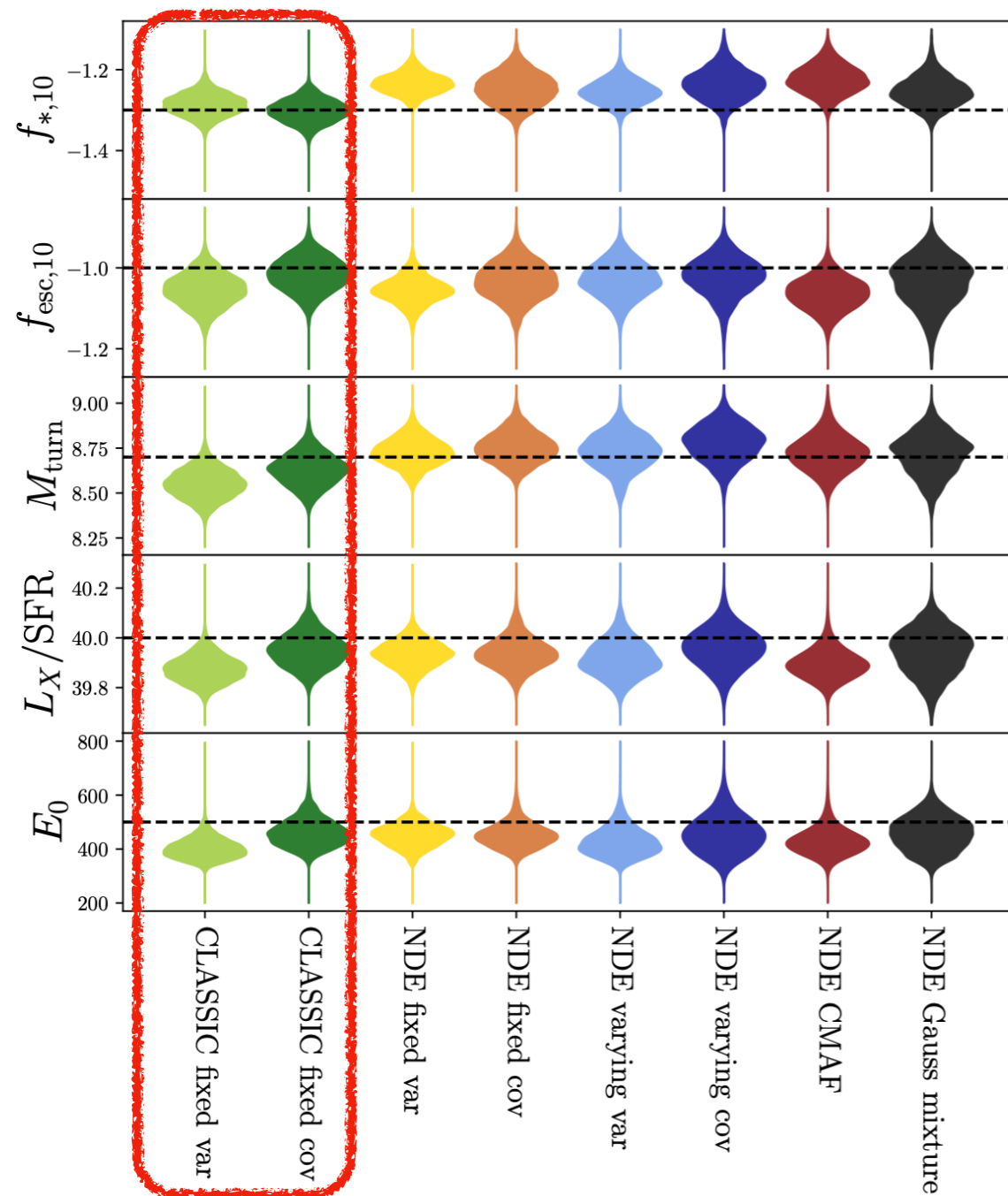
(Zhao+ 2022a)

**21cm image map can provide tighter constraints on EoR parameters than 21cm PS**

# Exploring the likelihood



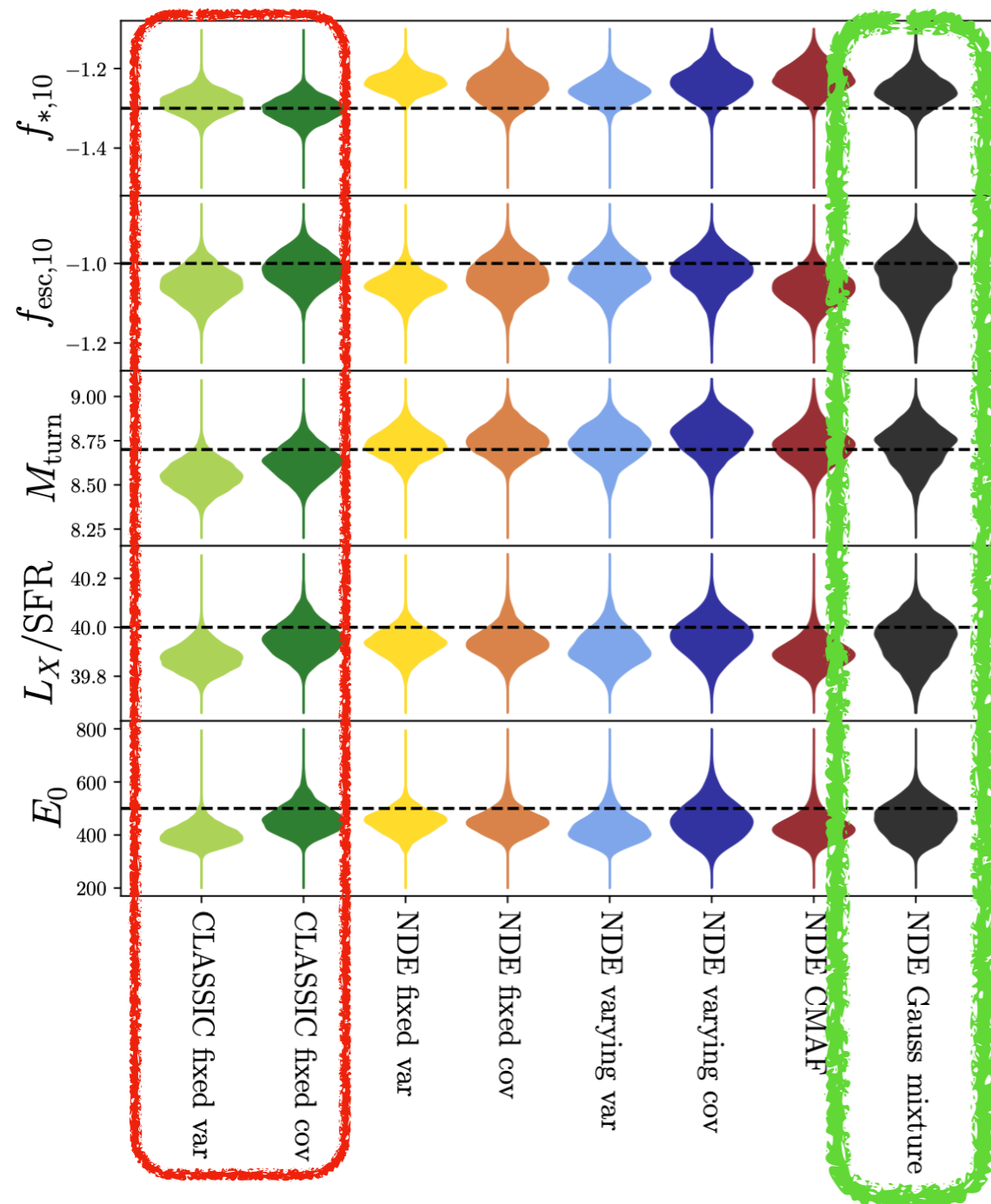
# Exploring the likelihood



- If **we include a covariance matrix** in Gaussian-likelihood, parameter inference is improved.



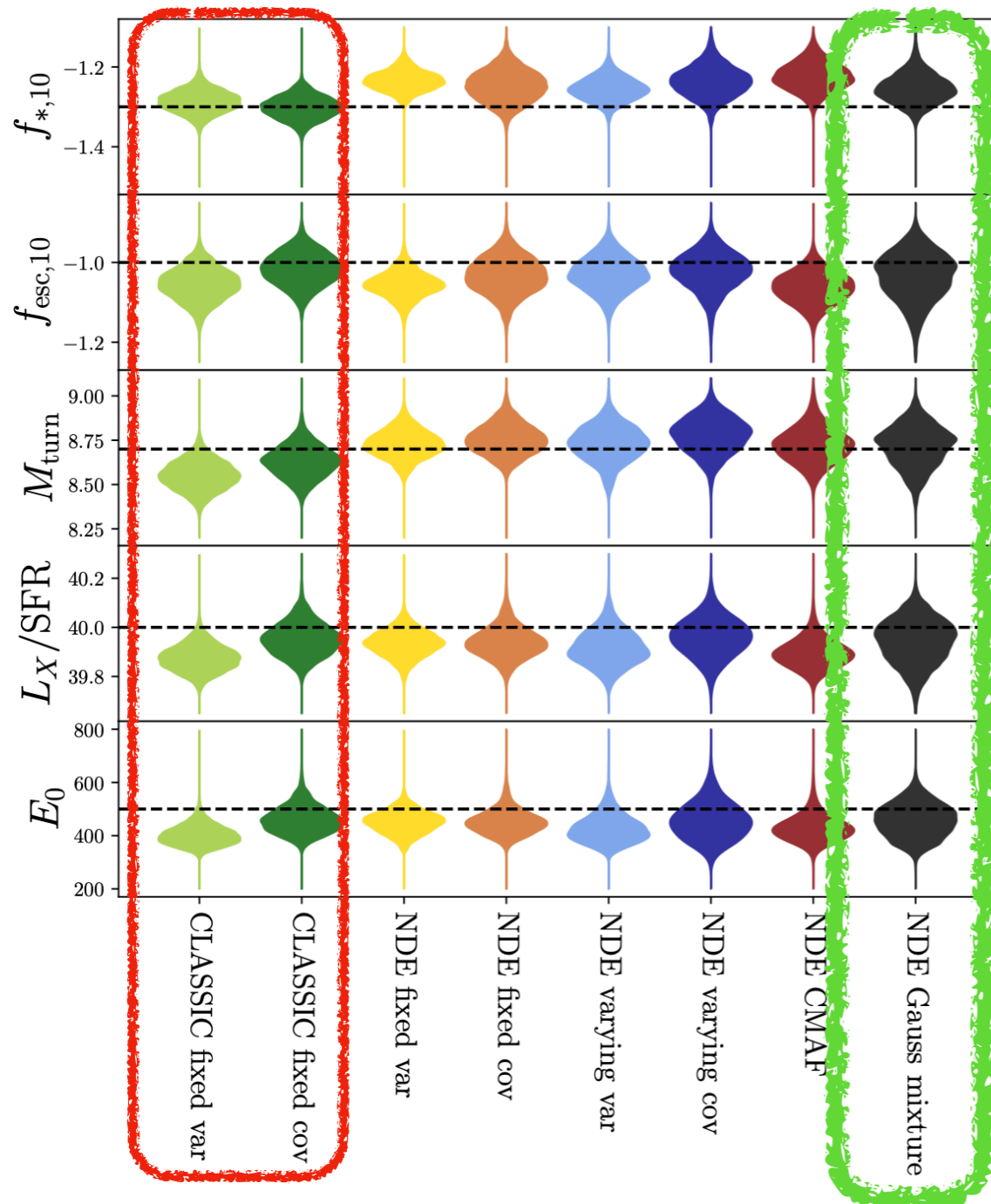
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The **non-Gaussian likelihood including covariance matrix** is better than the Gaussian likelihood for parameter inference from 21cm power spectrum.

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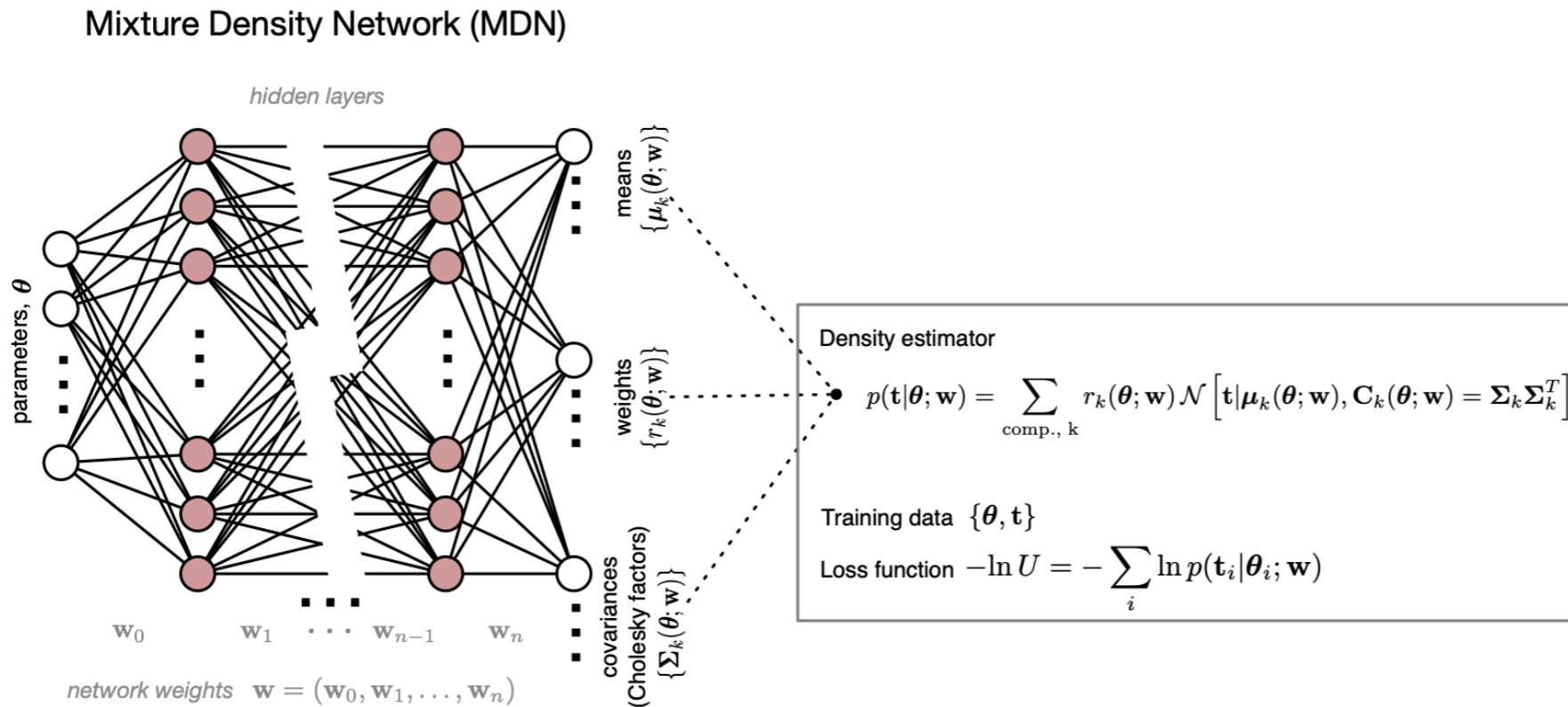
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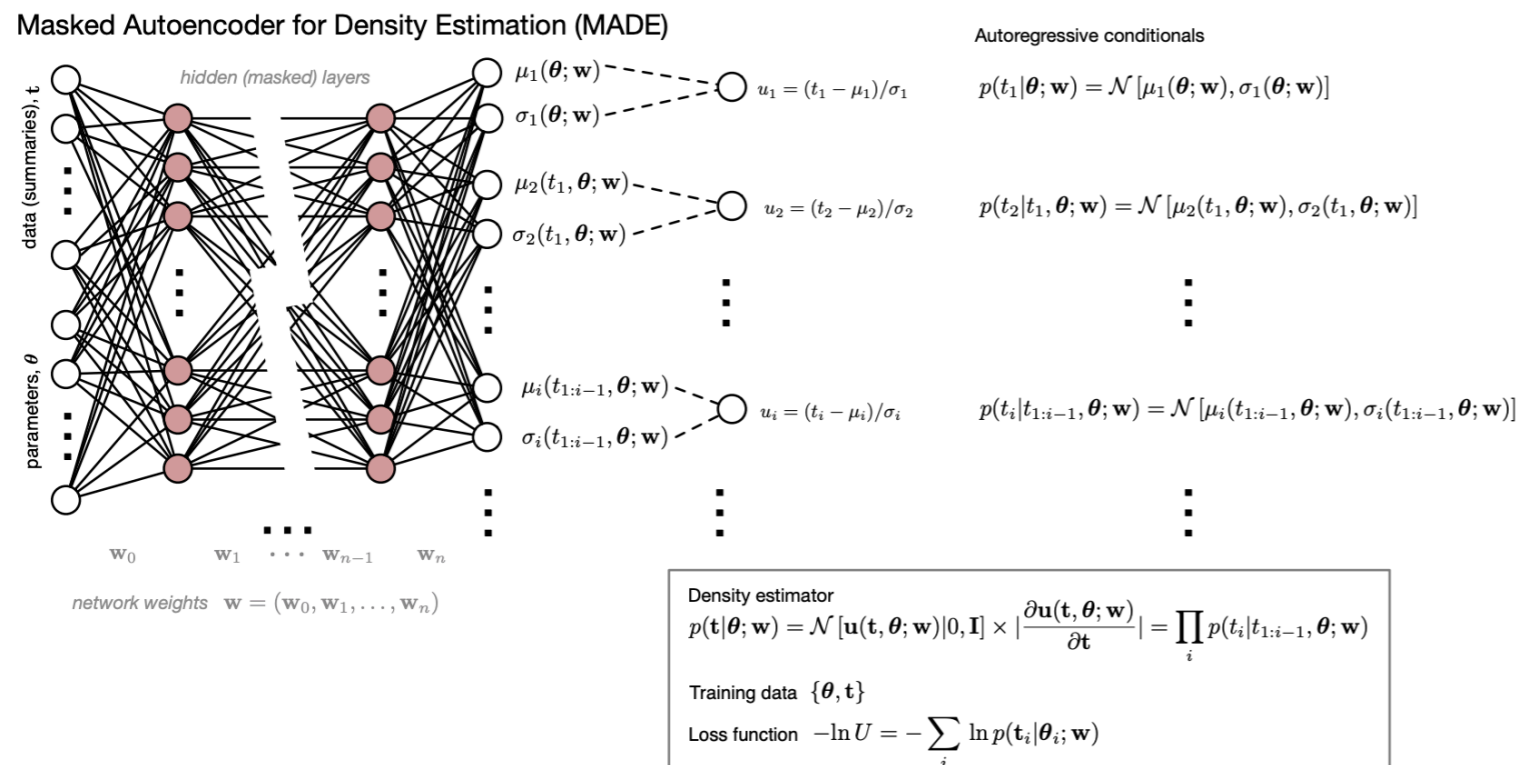
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# Mixture density networks(MDN) (Bishop 1994)



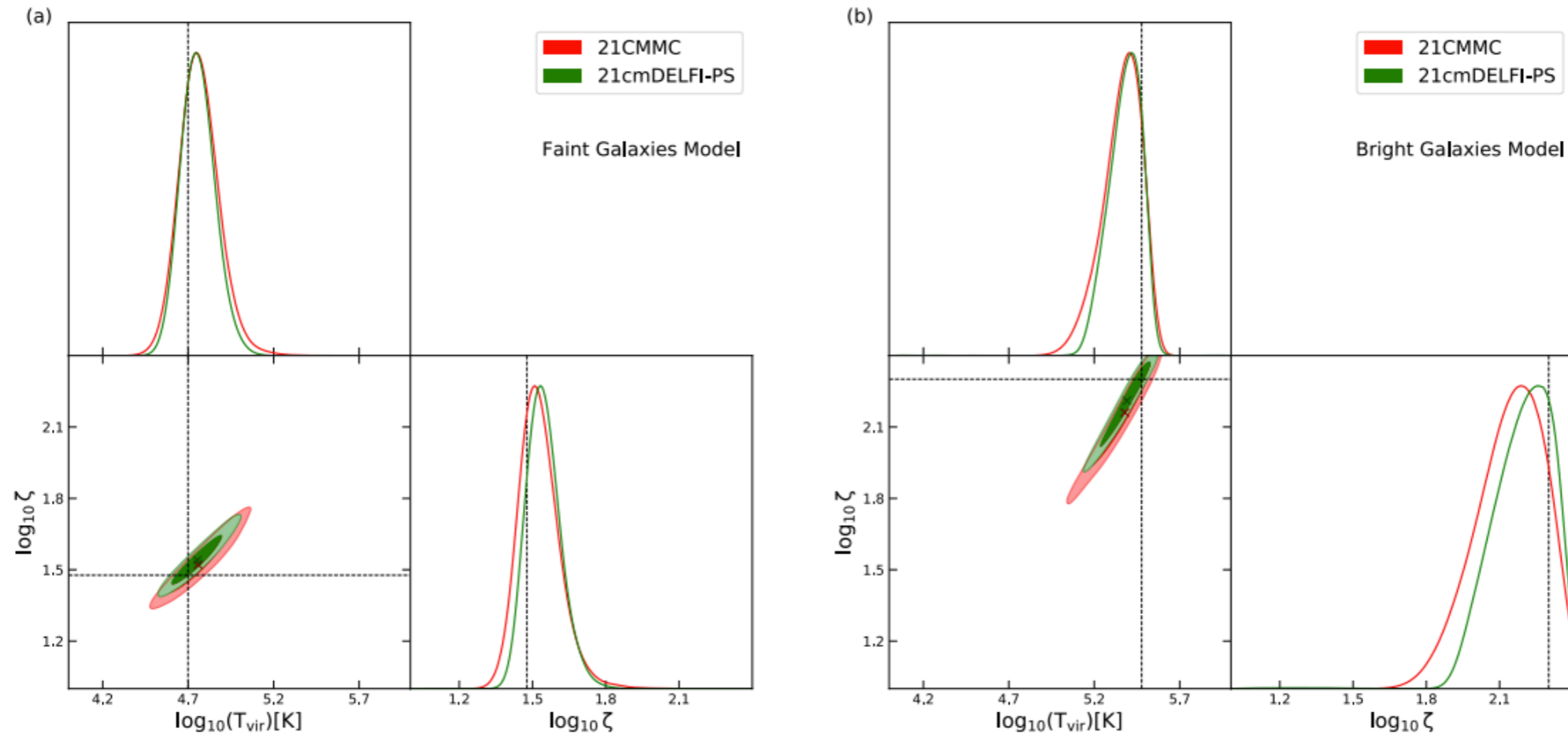
# Masked Autoencoder for Density Estimation (MADE) (Papamakarios et al 2017)



(See also Alsing+2019, Wang+2020)

# Comparing posteriors

- We can also compare the posterior obtained from 21cm PS by MCMC with posterior obtained by machine learning based approach (DELFI).



(Zhao+ 2022b)

- The posterior probability distribution can be obtained with the same accuracy when MCMC is performed and when DELFI is applied.